



# Microdrilling

EQUIPMENT / TECHNOLOGIES

	PSM-8	PSM-8B	PSM-8G	STM-8G	SM-14	PSM-16G	STM-16G
MICROPILES							
ANCHORINGS							
JET GROUTING	OPTIONAL KIT	OPTIONAL KIT	OPTIONAL KIT		OPTIONAL KIT	OPTIONAL KIT	
DOUBLE ROTARY ANCHORS / MICROPILE					OPTIONAL KIT		
VIBROROTARY					OPTIONAL KIT		
TOP HAMMER	OPTIONAL KIT	OPTIONAL KIT	OPTIONAL KIT		O OPTIONAL KIT	OPTIONAL KIT	
SOIL INVESTIGATION							
SOIL INVESTIGATION	OPTIONAL KIT	OPTIONAL KIT					
GEOTHERMAL							
TUNNELLING							
Special Applications					O CFA / PB	O CFA / PB	



= primary configuration



= optional kit available

PSM-20	SM-21	SM-30	ST-15	ST-20	ST-30	PST-60	ST-120	PSM-8GT	PSM-16GT
					OPTIONAL KIT				
OPTIONAL KIT	O OPTIONAL KIT		OPTIONAL KIT	OPTIONAL KIT	O OPTIONAL KIT				
O OPTIONAL KIT	O OPTIONAL KIT		OPTIONAL KIT	O OPTIONAL KIT	OPTIONAL KIT	OPTIONAL KIT	OPTIONAL KIT		
OPTIONAL KIT	OPTIONAL KIT								
O OPTIONAL KIT	O OPTIONAL KIT	O OPTIONAL KIT	OPTIONAL KIT	O OPTIONAL KIT	O OPTIONAL KIT	O OPTIONAL KIT	O OPTIONAL KIT		

# Microdrilling

#### Introduction

The use of micropiles in the special foundations field has found a steady development thanks to two main requirements: the possibility of consolidating soil while increasing their bearing capacity by means of compact size equipment with improved use flexibility and the possibility of using drilling technologies into loose soils which would be technically impossible to be faced by means of large diam. rigs, with a certain advantage in the execution times and methods.

The micropile mainly works with its point so that, whenever morphologic conditions allow it, we always attempt to introduce the point into the sound rock.

Therefore, the mostly used technologies are:

• DTH drilling and single rotation drilling (with helicoidal rods or rods and three-cones with air or water air outlet). In order to improve the execution, more complex technologies are used, such as **rotopercussion drilling with top** hammer (in the presence of rock), vibrorotary (with loss soils), cased drilling by single rotary (with odex, tubex, simmetrix and similar methods), and cased drilling with double rotary (with loss soil or under ground water). Diameters falling under the definition of micropile are up to 300 mm.

The cement grout following to drilling and reinforcement phases (with iron pipes, HB beams or cages) can be either by simple gravity or by high pressure.

This last solution allows a remarkable increase in the bearing capacity maintaining the same diameter.

Over the past few years, the trend involved a continuous increase in maximum diameters with sizes up to 600 mm, to be performed with the same types of hydraulic drill rigs.

The choice of the right micropile is anyway linked to and depends on various parameters, such as the soil mechanical features, the diameter to be executed, the most suitable drilling technique and, last but not least, criteria of economic criteria.

Soilmec covers all drilling methods and rigs suitable for executing small diameter consolidation into the micropile sector:

#### MICROPILES ANCHORINGS JETTING SOIL INVESTIGATIONS TUNNELLING GEOTHERMAL SPECIAL APPLICATIONS

The philosophy of the group is based on the construction of drilling equipment that can offer a high performance and allow, thanks to a modular design, the maximum flexibility of use in the site and which, at the same time, guarantees the choice and the application of various technologies in order to profitably drill any kind of soil.

Whereas strong specifications are requested, due to the nature of the work to be accomplished, rigs that are dedicated rigs - according to the technology they apply - have been designed and introduced, in view of their best use and operational result.



# **Micropiles and Anchoring**

### MICRODRILLING

The range consists of articulated hydraulic drills whose kinetic mechanism makes them suitable for creating micro-piles and anchoring at differing angles.

The articulated versions of Soilmec and PSM hydraulic drills currently range from 8 to 33 tons in weight, with different rotary strokes and mast lengths available, different rotary heads, different push-pull systems, and a wide range of optional accessories.

Micropiles are generally laid at angles no greater than 15°, but anchoring and/or drains may use assorted positioning techniques and particular kinetic mechanisms to achieve other angles.

On sites where it is possible to operate large-scale equipment a vertical 30 ton rig has been developed for diameters up to 500mm and depths up to 55m, exploiting mast length and using special loading systems.



#### Equipment

Model	<b>Torque</b> daNm	<b>Rotary stroke</b> mm	<b>Max (Rated) power</b> <i>kW</i>	Weight t	Kinetic mechanism
PSM-8	1024	3900	103 (85)	8.5-9.2	Combinated boom articulation
PSM-8G	916	3900	103 (85)	8.5	Fixed
PSM-16G	1024	4000	200 (176)	16	Fixed
PSM-8B	1024	3900	103 (85)	8.5	Complete boom articulation
SM-14	1207	4000/7000	123 (119)	13.5	Complete boom articulation
PSM-20	1747	7000/10000	155 (135)	20/22	Combinated boom articulation
SM-21	2025	4000÷7000/10000	188 (176)	21/23	Combinated boom articulation
SM-30	3659	14000	205 (164)	33	Parallelogram
ST-30*	2622	14000	153 (143)	32	Tunnel telescopic boom



#### **MICROPILES AND ANCHORING**

**The PSM-8 is a multipurpose drilling rig.** Its modular design is engineered for the execution of: Micropiles, Tie-backs, Jet-Grouting, Coring, Drain, Water wells.

The rig is fitted with proportional, hydraulic servo-assisted controls that make the operations smooth and trouble free even in the hardest working conditions.

Thanks to a particular kinematic mechanism (composed of: 650 mm extendable boom; swivelling  $\pm$  29°; joint 90°; motoreducer slew rig for radial drilling, optional) **the PSM-8 is a versatility unit that can be tailored to any customer need or geological conditions.** 

The PSM-8 may be further tailored with a wide range of optional items such as:

- Jet Grouting
- Mud pump (screw type fitted on board, triplex type for external use only)
- Top Hammer
- Rod carousel
- Slew ring < for radial drilling
- Radio operated remote control

Engine		DEUTZ TCD 2012 L04 Tier 3		
Power	kW	103 @ 2400 rpm		
Rated power	kW	85		
Hydraulic System				
Main numn	l/min	149		
Service pump	l/min	68+40+33+26		
Determ				
Rotary		HR-10 G		
Max torque	daNm@rpm	1024		
Rotation speed	rpm	381		
Mast feed/hoist system		Standard Optional		
Standard cradle stroke	mm	3845 2100		
Rod lenght	mm	3000 1500		
Max hoist force	kN	60		
Max feed force	kN	60		
Max speed (slow/fast)	rpm	0-17 / 35		
Clamp & Breaker				
Clamping range	mm	60-260		
Max clamping force	kN	110		
Max breaking torque	daNm	3600		
Service winch				
Max line pull 1st layer	kN	15		
Rope diameter	mm	10		
Undercarriage				
Track shoe width	mm	300		
Overall lenght	mm	2474		
Overall width	mm	1900		
Travelling speed	km/h	2,36		
Weight				
Total weight	ka	8500 / 0200		
Iotal weight	Kg	850079200		
Average pressure on ground	IVIPd	0,07		



### **Standard Version**











# PSM-8G

### **MICROPILES AND ANCHORING**

Designed mainly for geognostic use, it can be used for vertical drilling micropiles or inclined +/- 13°.

#### Main features:

- Rotation head with 6 ratio gearboxFixed kinetic mechanism

#### **Optional:**

- Jet-Grouting kit for treatments up to 12 m
- Mud pump screw type and triplex type fitted on board
- Wire-line winch
- Slew ring for inclinated drilling holes

Engine		DEUTZ TCD 2012 L04 Tier 3
Power	kW	103 @ 2400 rpm
Rated power	kW	85
Hudraulic Suctom		
Hyuraune System		
Main pump	l/min	149
Service pump	I/min	/1+46+29+23
Rotary		HR-9 coring
Max torque	daNm@rpm	916 @ 52
Rotation speed	rpm	0-832
Mast feed/hoist system		
Standard cradle stroke	mm	3750
Rod lenght	mm	3750
Max hoist force	kN	98
Max feed force	kN	73.6
Max speed (slow/fast)	rpm	11 (14) - 32 (44)
Clamp & Breaker		
Clamp & Breaker	mm	60-260
Clamp & Breaker Clamping range Max clamping force	mm kN	60-260 110
Clamp & Breaker Clamping range Max clamping force Max breaking torgue	mm kN daNm	60-260 110 3600
Clamp & Breaker Clamping range Max clamping force Max breaking torque	mm kN daNm	60-260 110 3600
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch	mm kN daNm	60-260 110 3600
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer	mm kN daNm kN	60-260 110 3600 15
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter	mm kN daNm kN mm	60-260 110 3600 15 10
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter Undercarriage	mm kN daNm kN mm	60-260 110 3600 15 10
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter Undercarriage Track shoe width	mm kN daNm kN mm	60-260 110 3600 15 10 300
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght	mm kN daNm kN mm mm	60-260 110 3600 15 10 300 2474
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width	mm kN daNm kN mm mm mm	60-260 110 3600 15 10 300 2474 1900
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed	mm kN daNm kN daNm kN daNm mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36 8200 / 9000
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight     Total weight     Average pressure on ground	mm kN daNm kN mm mm mm mm km/h km/h	60-260 110 3600 15 10 300 2474 1900 2,36 8200 / 9000 0.07

# PSM-8G

## **MICROPILES AND ANCHORING**



# Transport conditions





# **PSM-8B**

### **MICROPILES AND ANCHORING**

This crawler mounted drilling rig has a joint articulation of new design for the mast and an easy simple use. The unit is very versatile and suitable for specialized works such as: anchors, soil nails, tie-backs, micropiles, jet grouting, etc.

#### Main features of the rig are:

- Max torque: 1024 @ 381 rpm/max
- Rotary stroke with 2 options (short and long): 2065 mm or 3845 mm
- Hydraulic clamp and breaker: diam 60-260 m

#### A wide range of optional device are available such as:

- Mud pump (screw type fitted on board, triplex type for external use only)
- Jet grouting kit for mono, bi or three fluid (max treatment 12 m)
- Top hammer
- Special low headroom mast, stroke 2100 rpm

Engine		DEUTZ TCD 2012 L04
Power	kW	103 @ 2400 rpm
Rated power	kW	85
Hydraulic System		
	l /m in	140
Iviain pump	I/min	149
Service pump	1/11111	/1+40+29+23
Rotary		HR-10
Max torque	daNm	1024
Rotation speed	rpm	381
Mast feed/hoist system		
Standard gradle streke	mm	2015
Rod lenght	mm	3000
Max hoist force	kN	60
Max feed force	kN	60
Max speed (slow/fast)	rpm	0-17/35
Clamp & Breaker	_	
Clamp & Breaker Clamping range	mm	60-260
Clamp & Breaker Clamping range Max clamping force	mm kN	60-260 110
Clamp & Breaker Clamping range Max clamping force Max breaking torque	mm kN daNm	60-260 110 3600
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch	mm kN daNm	60-260 110 3600
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer	mm kN daNm kN	60-260 110 3600 15
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter	mm kN daNm kN mm	60-260 110 3600 15 10
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter	mm kN daNm kN mm	60-260 110 3600 15 10
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter Undercarriage	mm kN daNm kN mm	60-260 110 3600 15 10
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter Undercarriage Track shoe width Overall length	mm kN daNm kN mm	60-260 110 3600 15 10 300 2474
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width	mm kN daNm kN mm mm	60-260 110 3600 15 10 300 2474 1900
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width	mm kN daNm kN mm mm mm mm	60-260 110 3600 15 10 300 2474 1900 2 36
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed	mm kN daNm kN mm mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm km/h	60-260 110 3600 15 10 300 2474 1900 2,36 8000 / 8700

# PSM-8B

# **MICROPILES AND ANCHORING**



# Anchors version



# **Transport conditions**





# Working area



### **MICROPILES AND ANCHORING**

#### Soilmec SM-14 is a multipurpose drilling rig. Its modular design is engineered for the execution of:

Micropiles, Tie-backs, Jet-grouting, Drain, Water wells.

The rig is fitted with proportional, hydraulic servo-assisted controls that make the operations smooth. Featured with Load Sensing System, it has lower running costs and a reduced wear and tear on components.

#### Soilmec SM-14 versatility unit that can be tailored to any customer need or geological conditions:

- Available with a wide range of rotary heads ranging from 800 daNm to 2500 daNm (special attachment for each HR are available)

#### Soilmec SM-14 may be further tailored with a wide range of OPTIONAL items such as:

- Jet-grouting kit for mono, bi or three fluids treatment for ø 114 mm rods (ø 127 mm with special kit)
- Kinematic motion 90° mast articulation for tie-back and anchoring drilling (twin cylinders)
- Mast rotation by gearmotor for + 180°
- Service crane for handling of drilling rods and for rods & casing
- Designed for working with carousel
- Special mast stroke: 1500 1800 2100 3000 7000 mm
- Radio operated remote control
- Rod carousel 10x114 mm
- Double rotary head
- Grout pumps
- Mud pump

#### Several hydraulic rotary available with different regulation torque.



**Travelling Remote Board** 







Std. kinematic articulation 4x90° sector turntable

Engine		CUN	AMINS QSB 4.5	Tier 3
Power	kW	·	123 @ 2000 rp	m
Rated power	kW		l 19 @ 2200 rp	m
Hvdraulic Svstem				
Main pump	l/min		156	
Service pump	l/min	156		
Potany		ר		
	d a Nisa	HK-12		1500
Max torque	dainm	1207		1560
Rotation speed	rpm	0-221		0-184
Mast feed/hoist system		Standard (Cyli	nder) Optio	nal (Gear motor)
Standard cradle stroke	mm	4000		7000
Rod lenght	mm	3000		6000
Max hoist force	kN	89		87
Max feed force	kN	45		87
Max speed (slow/fast)	rpm	0-28		0-28
Clamp & Breaker		Standard	Ор	tional
Clamping range	mm	50-135	50-360	60-415
Max clamping force	kN	266	266	266
Max breaking torque	daNm	5060	5060	5060
Service winch				
Max line pull 1st laver	kN		20	
Rope diameter	mm		10	
Undercerriege				
Dhuercannage Frack shoo width	mm		400	
Nack Slide Width Overall lenght	mm		3062	
Overall width	mm		2300	
Travelling speed	km/h		2.7	
			,	
	lun -		12000 / 1 / 000	
Iotal weight Average prosente on ground	Kg MDo		13000 / 14000	)
average pressure on ground	IVIPa		0,07	



#### **MICROPILES AND ANCHORING**

## Standard version (Stroke 4000 mm cylinder)

## Optional version (Stroke 7000 mm gear motor)





Available: Optional kinematism 90° mast articulation and slew ring with motoreducer ( slewing boom articulation )

# **Transport conditions**



# **PSM-20**

### **MICROPILES AND ANCHORING**

The **PSM-20** is a multipurpose hydraulic drilling rig. Its modular design is engineered for the execution of micropiles, tiebacks, anchors, jet-grouting, drains, water wells. The rig is fitted with a proportional hydraulic system that makes drilling operations smooth and precise, even in the most difficult operating conditions.

#### The modular design of the PSM-20.

The stroke of the drilling rig can be varied from 7200 to 10200 mm (and vice versa) with a simple mast extension (or reduction) kit with hydraulic pipe rack. Various systems for the mechanical loading of the drilling rods are available with depths that range from 18 to 45 m for both vertical and inclined drilling of anchors or tie-backs. The particular kinematic mechanism with a 90° joint lets you drill anchors and tie-backs with the rotary drilling over the mast. This particular condition lets you reduce the mechanical consumption and friction and, in particular, work in total safety. The clamp/joint-breaker, thanks to a lifting system fitted with a hydraulic piston with a 600 mm stroke lets you extract the casings.

#### Various optional items and applicable technologies available:

- Top hammer
- Vibrorotary
- Double rotary
- Rotary with 133 mm inner diameter
- Jet Grouting for mono, bi and triple-fluid rods 90 mm max diameter with standard rotary
- Jet Grouting for mono, bi and triple-fluid rods 127 max with rotary type HR21G
- Hydraulic loader 2 x 6000 x 140 max
- Hydraulic rod loader 2 x 7500 x 127 max
- Carousel rod loader 6 x 4500 x 140 max
- Carousel rod loader 8 x 4500 x 114 mm
- Rods/casings lifting crane
- Radio control

Engine		DEUTZ TCD 20	)12 L06 Tier 3	
Power	kW	155 @ 2	400 rpm	
Rated power	kW	135		
Hudraulic System				
Hydraulic System	14.1			
Main pump	l/min	260		
Service pump	I/min	86+54+32+22+16		
Rotary		Standard HR-17 G	Option HR-21 G	
Max torque	daNm	1747	2154	
Rotation speed	rpm	295	315	
Mast feed/hoist system		Standard (Gear motor)	Ontional (Gear motor)	
Standard cradle stroke	mm			
Rod lenght	mm	6000	9000	
Max hoist force	kN	83	83	
Max feed force	kN	83	83	
May an and (alay) (fact)	rom	0.20	0.20	
wax speed (slow/fast)	rpm	0-28	0-20	
Max speed (slow/fast)	тртт	U-28 Standard	0-28 Ontional	
Clamp & Breaker	mm	0-28 Standard	Optional	
Clamp & Breaker Clamping range	mm kN	0-28 Standard 50-320 266	Optional 50-360	
Clamp & Breaker Clamping range Max clamping force Max breaking force	mm kN daNm	0-28 Standard 50-320 266 5060	0-28 Optional 50-360 170 7160	
Clamp & Breaker Clamping range Max clamping force Max breaking torque	mm kN daNm	0-28 Standard 50-320 266 5060	0-28 Optional 50-360 170 7160	
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch	mm kN daNm	0-28 Standard 50-320 266 5060	0-28 Optional 50-360 170 7160	
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer	mm kN daNm kN	0-28 Standard 50-320 266 5060 2	0-28 Optional 50-360 170 7160	
Clamp & Breaker Clamping range Max clamping force Max breaking torque Service winch Max line pull 1st layer Rope diameter	mm kN daNm kN mm	0-28 Standard 50-320 266 5060 2 2 1	0-28 Optional 50-360 170 7160 0 0	
Max speed (slow/rast)     Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage	mm kN daNm kN mm	0-28 Standard 50-320 266 5060 2 1	0-28 Optional 50-360 170 7160 0	
Max speed (slow/rast)     Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width	mm kN daNm kN mm	0-28 Standard 50-320 266 5060 2 1 50 50 50 50 50 50 50 50 50 50	0-28 Optional 50-360 170 7160 0 0 0	
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght	mm kN daNm kN mm mm	0-28 Standard 50-320 266 5060 2 1 1 50 2 2 1 50 250 250	0-28 Optional 50-360 170 7160 0 0 0 0 0 0 0 0 0 0 0 0 0	
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width	mm kN daNm kN mm mm mm	0-28 Standard 50-320 266 5060 2 1 50 2 1 50 25 29	0-28 Optional 50-360 170 7160 0 0 0 0 0 0 0 0 0 0 0 0 0	
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed	mm kN daNm kN mm mm mm mm km/h	0-28 Standard 50-320 266 5060 2 1 2 1 50 2 2 2 2 2 2 2 2 2 2 2 2 2	0-28 Optional 50-360 170 7160 0 0 0 0 0 0 0 0 0 0 0 0 0	
Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm km/h	0-28 Standard 50-320 266 5060 2 1 50 2 1 50 2 2 2 2 2 2 2 2 2 2 2 2 2	0-28 Optional 50-360 170 7160 0 0 0 0 0 0 0 0 0 0 0 0 0	
Max speed (slow/rast)     Clamp & Breaker     Clamping range     Max clamping force     Max breaking torque     Service winch     Max line pull 1st layer     Rope diameter     Undercarriage     Track shoe width     Overall lenght     Overall width     Travelling speed     Weight	mm kN daNm kN mm mm mm mm km/h	0-28 Standard 50-320 266 5060 2 1 50 2 2 2 2 2 2 2 2 2 2 2 2 2	0-28 Optional 50-360 170 7160 0 0 0 0 0 0 0 0 0 0 0 0 0	

PSM-20

#### **MICROPILES AND ANCHORING**



Working area

Articulation 90° opened



Articulation  $90^\circ$  closed





#### **MICROPILES AND ANCHORING**

**Soilmec SM-21** is a multipurpose drilling rig. Its modular design is engineered for the execution of: Micropiles, Tiebacks, Jet-grouting, Anchors, Water wells. Soilmec SM-21 is fitted with proportional, hydraulic servo-assisted controls so that drilling and positioning operations become easy, precise and smooth. The new hydraulic design optimizes the usage of the rig keeping the running cost down and powering any utility whenever required.

#### Soilmec SM-21 versatility unit that can be tailored to any customer need or geological conditions:

- Variable speed rotary head
- Top hammer
- Vibrorotary
- Double rotary
- Reverse circulation

#### Soilmec SM-21 standard version is already equipped with some important items:

- Foam pump
- Rod carousel for N°6 x 3000 mm long rods

#### Soilmec SM-21 may be further tailored with a wide range of OPTIONAL items such as:

- Jet-grouting: Soilmec SM-21 is able to reach treatment up to 20 m in single passage. The rotary hollow passage has now been increased to suit up to 140 mm o.d. rods
- Service crane for handling of drilling rods and for rods & casing
- Radio operated remote control, c/w hydraulic control panel
- Rod carousel. We also have the following options:
- N° 10 x 3000 mm; N° 10 x 4500 mm and  $\dot{N}^{\circ}2$  x 6000 mm long rods
- Double rotaryVibrorotary







DEUTZ TCD 2013 L06 2V Tier 3 Engine Power kW 188 **Rated power** kW 176 Hydraulic System Main pump 266 l/min 17+64+64+26 Service pump l/min Rotary HR-20 HR-37 2025 3659 Max torque daNm **Rotation speed** 179 127 rpm Cylinde Mast feed/hoist system Gear moto Standard cradle stroke 4800 7000 mm **Rod lenght** 3000 6000 mm Max hoist force kΝ 141 113 Max feed force 79 kΝ 113 Max speed (slow/fast) 0-24 0-29 rpm Standard Optional Clamp & Breaker 50-315 60-415 **Clamping range** mm Max clamping force kΝ 266 266 Max breaking torgue daNm 5060 5060 Service winch Max line pull 1st laver 20 kΝ **Rope diameter** 10 mm Undercarriage Track shoe width mm 500 **Overall lenght** mm 3631 **Overall width** 2500 mm 2,48 **Travelling speed** km/h Weight 21000 Total weight kq Average pressure on ground MPa 0,07

# SM-21

### MICROPILES AND ANCHORING



## Anchors - Tie back version



# 



## **Transport conditions**



# **SM-30**

### **MICROPILES AND ANCHORING**

Following the several requests for drilling micropiles and performing deep jet grouting treatments Soilmec designed the new SM-30 (multipurpose) hydraulic rig.

#### Main characteristics are:

- Depth: 55 m in jet grouting without manual operations
- Rotary feed stroke: 14,2 m
- Rotary torque: ranging from 1860 to 3659 daNm
- Rod feeder: n. 2 x 12 m rods
- Total operating weight: 33 tons
- Possibility to work with various rotaries, Top Hammers and DTH.

#### Additional technical features:

- Load sensing hydraulic system.
- Two main hydraulic pumps for a total delivery of 352 l/min, with variable displacement and constant power.
- All the movements are controlled by electro-hydraulic proportional joysticks, inside and outside the cabin, allowing the operator to work in the easiest way.
- Cable pull-down by 12 ton winch.
- Casing extractor (200 kN, stroke 750 mm)
- 3rd clamp for double string battery (rod and casing)

Engine     CUMMINS QSB 6.7C Tier 3       Power     kW     205	
Power kW 205	
Rated power kW 164	
Hydraulic System	
Main pumpI/min352	
<b>Service pump</b> I/min 96+37+24+20	
Rotary HR-20 HR-	37
Max torgue daNm 2025 36	59
Rotation speed rpm 0-117 0-8	33
Mart for all the interventions	
Mast reed/hoist system	
Standard cradle stroke mm 14200	
Rod lenght mm 12000	
Max hoist force kin 12	
Max reed force KN 12	
max speed (slow/fast) rpm 0-28	
Clamp & Breaker Standard Optional	
Clamping range mm 50-315 50-360	60-415
Clamping range     mm     50-315     50-360       Max clamping force     kN     266     266	60-415 266
Clamping range     mm     50-315     50-360       Max clamping force     kN     266     266       Max breaking torque     daNm     5060     5060	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchService winchService winch	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winch65	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Bone diametermm16	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchthe pull 1st layerkN65Rope diametermm16	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Rope diametermm16Undercarriage	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Rope diametermm16UndercarriageService width	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Rope diametermm16Undercarriagemm600Overall lenghtmm4510	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Rope diametermm16Undercarriagemm600Overall lenghtmm4510Overall widthmm2550 - 3700	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchMax line pull 1st layerkN65Rope diametermm16Undercarriagemm600Overall lenghtmm4510Overall widthmm2550 - 3700Travelling speedkm/h2,2	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchKN65Max line pull 1st layerkN65Rope diametermm16UndercarriageFrack shoe widthmmOverall lenghtmm4510Overall widthmm2550 - 3700Travelling speedkm/h2,2	60-415 266 5060
Clamping rangemm50-31550-360Max clamping forcekN266266Max breaking torquedaNm50605060Service winchKN65Max line pull 1st layerkN65Rope diametermm16UndercarriageTrack shoe widthmmOverall lenghtmm4510Overall widthmm2550 - 3700Travelling speedkm/h2,2Weightkq33000	60-415 266 5060

# SM-30

### **MICROPILES AND ANCHORING**

### **Standard Version**



# **Transport conditions**







#### **MICROPILES AND ANCHORING**

The ST-30 hydraulic tunnel machine is designed for sub-horizontal consolidation, for half-section or full-section drilling, up to a maximum height of 6.98 m from ground level.

A special accessories kit lets you use the equipment also for vertical or inclined drilling, for traditional consolidation or the invert of the tunnel with a stroke of 14 m and a max diameter of 114 mm. This feature means full-range use of the equipment for the best investment and operating flexibility.

### Tunnel version (5°)



\* double hydraulic system (diesel+electric)

Engine		DEUTZ TCD 2012 L06
Power	kW	153
Rated power	kW	143
Hvdraulic System*		
Main numn	l/min	297
Service pump	l/min	55+25
	0,11111	10.42
Rotary	1.00	HR-12
Max torque	daNm	1027
Rotation speed	rpm	221
Mast feed/hoist system		
Standard cradle stroke	mm	14000
Max hoist force	kN	84
Max feed force	kN	84
Max speed (slow/fast)	rpm	0-6-30
Clamp & Breaker		
Clamping range	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
Service winch		
Max line pull 1st layer	kN	20
Rope diameter	mm	10
Undercarriage		
Track shoe width	mm	600
Overall lenght	mm	3700
Overall width	mm	2500 - 3740
Travelling speed	km/h	1,5
Weight		
Total weight	ka	32000
Average pressure on ground	MPa	0.09
Average pressure on ground	ivii u	0,05

# ST-30

# **MICROPILES AND ANCHORING**





# Jet Grouting version





#### MICRODRILLING

#### **Technique**

Jet grouting technique consists of dissaggregating the soil and mixing it with cement mixtures.

#### MAIN APPLICATIONS:

- underpinning
- diaphragm walls
- tunnel consolidationsbottom plugs
- slopes consolidations
- dam cut-offs
- diaphragm walls gaps
- break-in and break-out for TBM

#### MAIN ADVANTAGES:

- wide range of soils that can be successfully treated.
- capability to obtain columns of consolidated soil with diameter ranging from 60 to more than 300 cm by using small diameter drilled holes, in general not larger than 100÷140 mm.
- capability to overpass pre-existing foundations, boulders, rocky layers.
- use of light weight and small size drilling rigs in small working areas.

#### **Drilling method**

Jet grouting techniques are world-wide classified into three categories according to the number of injected fluids: - mono-fluid system: cement grout is used as disaggregating and consolidating fluid (TREVIJET T1)

double-fluid system: cement grout plus air are used as disaggregating and consolidating fluid (TREVIJET T1/S)
triple-fluid system: water plus air are used as disaggregating fluid while cement grout is used as consolidating fluid (TREVIJET T2)

The site organization is very important for the three methods. The average total installed power is the following:

- mono-fluid system: 600+700 HP
- bi-fluid system: 700+800 HP
- triple-fluid system: 850÷1.000 HP

#### MONO-FLUID (up to 100 cm column dia.)

Simultaneous break-up and mixing of soil by a jet of cement grout. Rotary and Roto-Percussion drilling systems can be adopted by using the same jetting rods. The self-drilling monitor can be equipped with 1 or more jetting nozzles.

#### BI-FLUID (up to 250 cm column dia.)

Simultaneous break-up, partial removal and mixing of soil by a combined jet of cement grout plus air. Nozzles are designed to allow air-jet to create shroud around the grout-jet. By this effect the grout jet can be more efficient, maintaining sufficient energy to perform larger columns. Rotary and Roto-Percussion drilling system can be adopted by using the same jetting rods.

#### TRIPLE-FLUID (up to 300 cm column dia.)

Simultaneous break-up, partial removal of finer particles and mixing of soil by jets respectively of water plus air, and cement grout. Rotary drilling systems can be adopted by using the same jetting rods. In case of difficult soils, drilling operations have to be performed with an auxiliary roto-percussion drilling string.





MICRODRILLING





# MICRODRILLING





### MICRODRILLING

All models in the SOILMEC/PSM range are suitable for jet grouting.

It is possible to choose the jet grouting configuration when first setting up, from the wide range of rotaries, with an internal tube from 93 to 143 mm, together with the matching chuck, for column treatments up to 3000 mm in diameter and compatible with the type of soil.

Drills initially designed for other technologies may also be adapted for jet grouting using the appropriate transformation kits available for individual models.

Single pass treatments, starting from 12 m are possible with the PSM 8, the lightest rig in the range, then up to 36 m with the special SM-30 that, with the aid of a special loading system, can reach a depth of 55 m.

Model	<b>Treatment depth</b>	Allowed rod diameter mm
PSM-8	12	76 (90)
PSM-8B	12	76 (90)
SM-14	16	114 (127)
PSM-20	21	90 (127)
SM-21	20	140

**Drill with COMPLETE BOOM** ARTICULATION AND COMBINATED **BOOM ARTICULATION** 

Drill	wi	th		
FIXE	DK	(IN	ET	IC

**Drill with** 

Model	<b>Treatment depth</b>	Allowed rod diameter
PSM-8G	12	76 (90)
PSM-16G	16	127
SM-30 *	32	140
ST-30 (Vertical version)	25	114 (127)

\* special equipment with triangular support, SR-30 derivation.

Urill with TUNNEL TELESCOPIC BOOM	Model	<b>Treatment depth</b>	Allowed rod diameter mm
	ST-15	11	114 (127)
	ST-20	14.2 - 16	114
	ST-30	14	114 (127)
	PST-60	24	90 (127)
	ST-120	24	90 (127)

## MICRODRILLING

SOILMEC pumps are used for high pressure grout technologies for soil consolidations.

The experience gained in the oil field as well as in soil improvement over the last two decades, has enabled to develop sturdy and reliable.

Soilmec pumps are mechanically driven through a system made of clutch, gearbox, cardan joint and chain.

#### **Optional items:**

- Diesel engines of different brands
- Booster pump
- Visualizing and recording devices for treatment parameters
- Container or skid-mounted version



Model	<b>Max pressure</b> bar (psi)	Max delivery lt./min (G,P,M.)	Nominal power kW (HP)
5T-400J	900 (13.050)	442 (116)	298 (400)
7T-500J	900 (13.050)	599 (158)	373 (500)
7T-600J	800 (11.600)	760 (200)	447 (600)
7T-800J	750 (10.880)	614 (162)	597 (800)
7T-1000J	800 (11.600)	682 (180)	746 (1000)

#### Notes:

1) Volumetric efficiency :100%.

2) Mechanical efficiency: 90%

# High pressure pumps

# **JET GROUTING - JOB SITE ACCESSORIES**

### **Containerized version**



#### Only for 5T-400J, 7T-500J e 7T-600J

#### **Skid version**





# **High Pressure Pumps**

# **JET GROUTING - JOB SITE ACCESSORIES**

5T-400J		
Plunger diameter	in	<b>3 - 3</b> 1/2 <b>- 4</b>
Stroke	in	5
Max discharge press.	bar (P.S.I.)	900 (13.050)
Max delivery	l/min (G.P.M.)	442 (116)
Nominal power	kW (HP)	298 (400)
Mass (approx.)	kg (Ibs)	12.500 (27.560)



7T-500J		
Plunger diameter	in	3 - 3 1/2 - 4
Stroke	in	7
Max discharge press.	bar (P.S.I.)	900 (13.050)
Max delivery	l/min (G.P.M.)	599 (158)
Nominal power	kW (HP)	373 (500)
Mass (approx.)	kg (lbs)	13.400 (29.550)



7T-600J		
Plunger diameter	in	<b>3</b> 1/2 - <b>4</b> - <b>4</b> 1/2
Stroke	in	7
Max discharge press.	bar (P.S.I.)	800 (11.600)
Max delivery	l/min (G.P.M.)	760 (200)
Nominal power	kW (HP)	447 (600)
Mass (approx.)	kg (Ibs)	14.000 (30.870)



# High pressure pumps

# **JET GROUTING - JOB SITE ACCESSORIES**

7T-800J		
Plunger diameter	in 3	1/2 - 4 - 4 1/2 - 4 3/4
Stroke	in	7
Max discharge press.	bar (P.S.I.)	750 (10.880)
Max delivery	l/min (G.P.M	.) <b>614 (162)</b>
Nominal power	kW (HP)	597 (800)
Mass (approx.)	kg (lbs)	23.000 (50.700)





7T-1000J		
Plunger diameter	in	<b>4 - 4</b> 1/2 <b>- 4</b> 3/4 <b>- 5</b>
Stroke	in	7
	4 4	
Max discharge press.	bar (P.S.I.)	800 (11.600)
Max delivery	l/min (G.P.M.)	682 (180)
Nominal power	kW (HP)	746 (1.000)
Mass (approx.)	kg (lbs)	24.000 (52.900)



# PSM-8 / PSM-8B

# JET GROUTING - COMPLETE AND COMBINATED BOOM ARTICULATIONS RIG

To use 90 mm diameter rods the optional HR-10 G rotary is required. Systems for measuring and recording the drilling parameters can be fitted.

		PSM-8	PSM-8B
Max treatment	mm	12000	12000
Max rod diameter	mm	76÷90	76÷90
Operative weight (jet grouting configuration)	kg	9200	8800
Engine			
Power	kW	103	103
Rated power	kW	85	85
Hydraulic System			
Main pump	l/min	149	149
Service pump	I/min		
Rotary		HR-10	HR-10
Max torque	daNm	1024	1024
Rotation speed	трш	362	302
Mast feed/hoist system			
Standard cradle stroke	mm	3845	3845
Max hoist force	kN	60	60
Max feed force	kN	60	60
Max speed (slow/fast)	rpm	0-17 / 35	0-17 / 35
Clamp & Breaker			
Clamping range	mm	60-260	60-260
Max clamping force	kN	110	110
Max breaking torque	dainm	3600	3600
Service winch	1.5.5		
Max line pull 1st layer	kN	15	15
Rope diameter	111111	10	10
Undercarriage		200	200
Irack shoe width Overall lenght	mm	300	300
Overall width	mm	1900	1900
Travelling speed	km/h	2,36	2,36
Weight			
Total weight	kg	8500 / 9200	8000 / 8800
Average pressure on ground	MPa	0,07	0,07

# PSM-8 / PSM-8B

**JET GROUTING - COMPLETE BOOM ARTICULATION** 



The SM-14 is very versatile and particularly suitable for jet grouting, with an appropriate transformation kit.

- Max depth treatment: 16 m (monofluid system) and 15,4 (bifluid/trifluid system) with rod up to 127 mm diameter c/w special adapter kit
- Systems for measuring and recording the drilling parameters can be fitted
- Variable rotary available

Max treatment	mm	15400 ÷ 16000		
Max rod diameter	mm	90 - 114 - 127		
Operative weight (jet grouting configuration)	kg	13800		
Engine		CUN	1MINS QSB 4.5	Tier 3
Power	kW	1	23 @ 2000 rp	m
Rated power	kW	1	19 @ 2200 rp	m
Hydraulic System				
Main pump	l/min		156	
Service pump	l/min		156	
Rotary		HR-12		HR-16G
Max torque	daNm	1207		1560
Rotation speed	rpm	0-221		0-184
Mast feed/hoist system		Standard (cylir	nder) Optio	nal (gear motor)
Standard cradle stroke	mm	4000		7000
Kod lenght Max hoist force	mm kn	3000		6000 87
Max field force	kN	45		87
Max speed (slow/fast)	rpm	0-28		0-28
Clamp & Breaker		Standard	Op	tional
Clamping range	mm	50-315	50-360	60-415
Max clamping force	kN	266	266	266
Max breaking torque	dainm	5060	5060	5060
Service winch				
Max line pull 1st layer	kN		20	
Rope diameter	(f)(f)		10	
Undercarriage			40.0	
Track shoe width	mm	400		
Overall width	mm	2300		
Travelling speed	km/h	2,7		
Weight				
Total weight	kg		13000 / 14000	)
Average pressure on ground	MPa	0,07		



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The PSM-20 hydraulic drilling rig, with the relevant kit, lets you execute jetting treatments down to a depth of 21 m without the use of rod loaders.

The jet grouting kit has a special telescopic extension. In fact, the jet extension guided by the rotation head, slides on the main mast so you can transport the rig at the end of the job with the kit completely mounted and ready for use on another site.

90 mm diameter rods are used with the standard rotary.

To use 127 mm diameter rods, the optional HR-21 rotary is required.

Systems for measuring and recording the drilling parameters can be fitted.

Max treatment	mm	21000		
Max rod diameter	mm	90 (127*)		
Operative weight (jet grouting configuration)	kg	21500 ÷ 22500		
Engine		DEUTZ TCD 2012 L06 Tier 3		
Power	kW	155 @ 2	400 rpm	
Rated power	kW	13	35	
Hydraulic System				
Main pump	l/min	26	50	
Service pump	l/min	86+54+3	2+22+16	
Rotary		Standard HR-17	Option HR-21 (Gear motor)	
Max torque	daNm	1747	2154	
Rotation speed	rpm	295	315	
Mast feed/hoist system		Standard (Gear motor)	Optional (Gear motor)	
Standard cradle stroke	mm	7200	10200	
Rod lenght	mm	6000	9000	
Max hoist force	kN	83	83	
Max feed force	kN	83	83	
Max speed (slow/tast)	rpm	0-28	0-28	
Clamp & Breaker		Standard	Optional	
Clamping range	mm	50-320	50-360	
Max clamping force	kN	266	170	
Max breaking torque	daNm	5060	7160	
Service winch				
Max line pull 1st layer	kN	2	0	
Rope diameter	mm	1	0	
Undercarriage				
Track shoe width	mm	50	00	
Overall lenght	mm	25	00	
Overall width	mm	2900		
Travelling speed	km/h	2,0		
Weight				
Total weight	kg	20000 -	- 24000	
Average pressure on ground	MPa	0,07		

\* optional rotary, 127 mm 34

# **PSM-20**

# JET GROUTING - COMPLETE BOOM ARTICULATION

Closed version with low rotary

#### Max version with rotary on top (max treatment 21 m in monofluid version)







The new SM-21 is very versatile and particularly suitable for jet grouting, with an appropriate transformation kit.

- Max treatment depth: 20 m single passage and 51 m with rod carousel
- Systems for measuring and recording the drilling parameters can be fitted.

Max treatment	mm	20000		
Max rod diameter	mm	140		
Operative weight (jet grouting configuration)	kg	22000 ÷	- 24000	
Engine		DEUTZ TCD 2013 L06 2V Tier 3		
Power Poted power	kW	18	88	
Rated power	KVV	17	0	
Hydraulic System	1/100100	20		
Main pump Service pump	I/min	20 بـ 17ـــ6/	00 -64+26	
Determ	1/11111			
Kulary Max targua	daNm	HK-20	HK-37 2650	
Rotation speed	rom	179	127	
		Culturalor	Coortestor	
Standard gradie streke	mm			
Rod lenght	mm	3000	6000	
Max hoist force	kN	141	113	
Max feed force	kN	79	113	
Max speed (slow/fast)	rpm	0-24	0-29	
Clamp & Breaker		Standard	Optional	
Clamping range	mm	50-315	60-415	
Max clamping force	kN	266	266	
Max breaking torque	daNm	5060	5060	
Service winch				
Max line pull 1st layer	kN	2	0	
Rope diameter	mm	1	0	
Undercarriage				
Track shoe width	mm	500		
Overall lenght	mm	3631		
Uverall width	mm km/b	2500		
navening speed	K1(1/11	km/n 2,48		
Weight				
Total weight	kg	21000		
Average pressure on ground	MPa	0,07		






**JET GROUTING - COMPLETE BOOM ARTICULATION** 



## PSM-8G

#### **JET GROUTING - FIXED KINEMATIC**

The **PSM-8G** hydraulic drilling rig, with the relevant kit, lets you execute jetting treatments down to a depth of 12 m without the use of rod loaders. The jet grouting kit has a special telescopic extension.

The jet extension in fact, guided by the rotary head, slides on the main mast so you can transport the rig at the end of the job with the kit completely mounted and ready for use on another site.

- 76 mm rods are used with the standard rotary
- To use 90 mm diameter rods the optional HR-9L coring rotary is required

Systems for measuring and recording the drilling parameters can be fitted

Max treatment	mm	12000
Max rod diameter	mm	76 (90)
Operative weight (jet grouting configuration)	kg	9200
Engine		DEUTZ TCD 2012 L04
Power	kW	103 @ 2400 rpm
Rated power	kW	85
Hydraulic System		
Main pump	l/min	149
Service pump	l/min	71+46+29+23
Rotary		HR-9 coring
Max torque	daNm@rpm	916 @ 52
Rotation speed	rpm	0-832
Mast feed/hoist system		
Standard cradle stroke	mm	3900
Rod lenght	mm	3000
Max hoist force	kN	98
Max feed force	kN	73,6
Max speed (slow/tast)	rpm	11 (14) - 32 (44)
Clamp & Breaker		
Clamping range	mm	60-260
Max clamping force	kN	110
Max breaking torque	daNm	3600
Service winch		
Max line pull 1st layer	kN	15
Rope diameter	mm	10
Undercarriage		
Track shoe width	mm	300
Overall lenght	mm	2474
Overall width	mm	1900
Travelling speed	km/h	2,36
Weight		
Total weight	kg	8200 ÷ 9000
Average pressure on ground	MPa	0,07



JET GROUTING - FIXED KINEMATIC



## **PSM-16G**

#### **JET GROUTING - FIXED KINEMATIC**

The PSM-16G drilling rig with the special kit can execute column jet grouting to a depth of 16 m (monofluid system).

#### **Optional tools:**

- Thrust block with pistons on mast for drilling inclined piles
- Ready for systems to record drilling parameters

Max treatment	mm	90 (127)
Max rod diameter	mm	16
Operative weight (jet grouting configuration)	kg	15000 - 17000
Engine		DEUTZ TCD 2013 L06 2V
Power	kW	200@2400 rpm
Rated power	kW	176 @ 1900 rpm
Hydraulic System		
Main pump	l/min	280
Service pump	l/min	142+64+44+22
Rotary		HR-10 coring
Max torque	daNm@rpm	1024
Rotation speed	rpm	1000
Mast feed/hoist system		
Standard cradle stroke	mm	4000
Rod lenght	mm	3000
Max hoist force	KN KN	195
Max speed (slow/fast)	rpm	0.14 - 0.58
Clamp & Breaker		
Clamping range	mm	60-320
Max clamping force	kN	340
Max breaking torque	daNm	8600
Service winch		
Max line pull 1st layer	kN	30
Rope diameter	mm	14
Undercarriage		
Track shoe width	mm	400
Overall lenght	mm	2760
Overall width	mm	2300
navening speed	K[1]/[]	23
Weight		
Total weight	kg	15000 - 17000
Average pressure on ground	IVIPa	U, /

## PSM-16G

### **JET GROUTING - FIXED KINEMATIC**



## Transport conditions



#### **JET GROUTING - FIXED KINEMATIC**

The SM-30 hydraulic drilling rig is designed for particularly difficult jobs working at great depth with excellent jetting performance.

- Depths of 55.5 m can be reached using 140 mm diameter rods with a rod loader
- Systems for measuring and recording the drilling parameters can be fitted
- Single jetting treatments can be executed to a depth of 31.5 m

Single pass treatment	mm		31500			
Max treatment	mm	55000				
Max rod diameter	mm		140			
Operative weight (jet grouting configuration)	kg	34000				
Engine		CUMI	MINS QSB 6.7C 1	Tier 3		
Power	kW		205			
Rated power	kW		164			
Hydraulic System						
Main pump	l/min		352			
Service pump	l/min		96+37+24+20			
Rotary		HR-20		HR-37		
Max torque	daNm	2025		3659		
Rotation speed	rpm	0-117		0-83		
Mast feed/hoist system						
Standard cradle stroke	mm		14200			
Rod lenght	mm		12000			
Max hoist force	kN kN	12				
Max speed (slow/fast)	rnm		0-28			
Clamp & Brooker		Standard		ional		
Clamping range	mm	50 215	50 260			
Max clamping force	kN	266	266	266		
Max breaking torque	daNm	5060	5060	5060		
Service winch						
Max line pull 1st laver	kN		65			
Rope diameter	mm		10			
Undercarriage						
Track shoe width	mm		600			
Overall lenght	mm	4510				
Overall width	mm		2550 - 3700			
iravening speed	km/h		2,2			
Weight						
Total weight	kg		33000			
Average pressure on ground	MPa		0,082			



#### **JET GROUTING - FIXED KINEMATIC**



## **Transport conditions**







Designed for use in the tunnelling version, the new ST-15 can be executed jet grouting method with the relevant kit.

#### **Optional devices:**

- Systems for measuring and recording the drilling parameters can be fitted

See the working area in the section Tunnelling pag. 66

Max treatment	mm	11250
Max rod diameter	mm	90 (127)
Operative weight (jet grouting configuration)	kg	12750
Engine		DEUTZ BF4M 2012
Power	kW	92
Rated power	kW	85
Electric motor (optional)	kW	90
Hydraulic System*		
Main pump	l/min	221 (28)
Service pump	l/min	54 (25)
Potany		
Notary	al a N Ivaa	1020
Max torque	dainm	1028
Rotation speed	трш	147
Mast feed/hoist system		Winch
Standard cradle stroke	mm	7000
Rod lenght	mm	6000
Max hoist force	kN	52
Max feed force	kN	52
Max speed (slow/tast)	rpm	7-25
Clamp & Breaker		
Clamping range	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
Undercarriage		
Track shoe width	mm	350
Overall lenght	mm	2544
Overall width	mm	2100
Travelling speed	km/h	2,1
Weight		
Total weight	ka	12250
Average pressure on ground	MPa	0,09

\* double idraulic system (diesel+electric)

### JET GROUTING - TUNNELLING RIG

### **Working Condition Std**





### Working Condition with extension





Transport conditions (Standard version)





Designed for use in the tunnelling version, the new ST-20 can be executed the jet grouting method with the relevant kit.

- Systems for measuring and recording the drilling parameters can be fitted.

See the working area in the section Tunnelling pag. 66

Max treatment	mm	22000
Max rod diameter	mm	90 (127)
Operative weight (jet grouting configuration)	kg	12750
Engine		DEUTZ TCD 2013 L04 2V
Power	kW	129@2400 rpm
Rated power	kW	116@1900 rpm
Electric motor	kW	90
Hydraulic System*		
Main pump	l/min	150
Service pump	l/min	86+86+34+22+22+12
Rotary		HR-10
Max torque	daNm	1028
Rotation speed	rpm	147
Mast feed/hoist system		Winch
Standard cradle stroke	mm	14200
Max hoist force	kN	67
Max feed force	kN	67
Max speed (slow/fast)	rpm	9/32
Clamp & Breaker		
Clamping range	mm	60-225
Max clamping force	kN	149
Max breaking torque	daNm	3830
Undercarriage		
Track shoe width	mm	400
Overall lenght	mm	3280
Overall width	mm	2490
Travelling speed	km/h	1,63
Weight		
Total weight	kg	21000
Average pressure on ground	MPa	0,10

\* double idraulic system (diesel+electric)













Designed for use in the tunnelling version, the new ST-30 can be executed the jet grouting method with the relevant kit.

#### **Optional device:**

- Systems for measuring and recording the drilling parameters can be fitted.

See the working area in the section Tunnelling pag. 66





Radio Remote Control

Max treatment	mm	16000
Max rod diameter	mm	114
Operative weight (jet grouting configuration)	kg	28000-30000
Engine		DEUTZ TCD 2012 L06 2V
Power	kW	153
Rated power	kW	143
Hydraulic System*		
Main pump	l/min	297
Service pump	l/min	55+25
Rotary		HR-12
Max torque	daNm	1027
Rotation speed	rpm	221
Mast feed/hoist system		
Standard cradle stroke	mm	14000
Max hoist force	kN	84
Max feed force	kN	84
Max speed (slow/fast)	rpm	0-6-30
Clamp & Breaker		
Clamping range	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
Undercarriage		
Track shoe width	mm	600
Overall lenght	mm	3740
Overall width	mm	2500 - 3740
Iravelling speed	km/h	1,5
Weight		
Total weight	kg	32000
Average pressure on ground	MPa	0,09
double bydraulic system (diocal u electric)		

\* double hydraulic system (diesel+electric)



3°

3° ∽

2200

3400

3524

600



Designed for use in the tunnelling version, the new PST-60 can be modified for the jet grouting method with the relevant kit.

#### **Optional device:**

- System for adjusting drilling parameters.

Max treatment	mm	24000
Max rod diameter	mm	90 (127*)
Operative weight (jet grouting configuration)	kg	64000-66000
Engine		DEUTZ TCD 2012 L06
Power	kW	155
Rated power	kW	135
Electric motor	kW	118
Hydraulic System		
Main pump	l/min	250
Service pump	l/min	90+50+30+30
Rotary		HR-17 G
Max torque	daNm	1747
Rotation speed	rpm	295
Mast feed/hoist system		
Standard cradle stroke	mm	19000 (24000 with ext.)
Max hoist force	kN	7
Max feed force	kN	7
Max speed (slow/fast)	rpm	26
Clamp & Breaker	·	
Clamping range	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
Undercorrigge		
Track shop width	mm	600
Overall lengt	mm	4510
Overall width	mm	2500 (3700)
Travelling speed	km/h	200 (5700)
	N111/11	
Weight		
Total weight	kg	64000 / 66000
Average pressure on ground	MPa	1,1

\* ø 127 mm with optional rotary HR-21









Designed for use in the tunnelling version, the new ST-120 can be modified for the jet grouting method with the relevant kit.

#### **Optional device:**

- Systems for measuring and recording the drilling parameters can be fitted

See the working area in the section Tunnelling pag. 66

Max treatment	mm	24000
Max rod diameter	mm	114
Operative weight (jet grouting configuration)	kg	11800
Engine		CUMMINS QSB 6.7
Power	kW	164
Rated power	kW	135
Electric motor	kW	90x2
Hydraulic System*		
Main pump	l/min	214x2
Service pump	l/min	142/2x(158+158)+2x+158
Rotary		HR-12
Max torque	daNm	1207
Rotation speed	rpm	221
Mast feed/hoist system		
Standard cradle stroke	mm	16000 / 18000 / 21000 / 24000
Max hoist force	kN	84
Max feed force	kN	84
Max speed (slow/fast)	rpm	5-30
Clamp & Breaker		
Clamping range	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
Undercarriage		
Track shoe width	mm	800
Overall lenght	mm	5000
Overall width	mm	3900
Travelling speed	km/h	1,35 / 0,84
Weight		
Total weight	kg	115000
Average pressure on ground	MPa	0,19

## JET GROUTING - TUNNELLING RIG

Working configuration 21 m











### **JET GROUTING - TUNNELLING RIG**

#### **Tilting Configuration**





#### **Transport conditions**



## JET GROUTING - TUNNELLING RIG



## Soil Investigation

#### MICRODRILLING

Soilmec has created a range of hydraulic probes especially for soil investigation.

Operations performed for soil investigation can be broken down into three main categories:

- Geo-technical investigation (defining soil characteristics)
- Geo-mechanical investigation (analysis of the mechanical behaviour of rocky masses)
- Geo-physical investigation (analysis of the dynamic behaviour of soils and their deformability)

For all these main purposes, the use of appropriate core-boring systems is necessary when taking soil samples for subsequent analysis in a laboratory or onsite, in order to define the morphological stratigraphy of the soil under investigation.

The information thus acquired influences and makes it possible to choose the most appropriate type of foundations and the most suitable drilling technology, in both technical and economic terms and according to the way they are to be executed.

**Geo-technical and geo-mechanical investigations** are carried out using conventional or variable diameter wireline core-boring.

Core-boring defined as **conventional** uses:

- Type B core barrels B (single)
- Type T2 double core barrels
- Type T6 double core barrels
- Type T6S double core barrels

Special additional sample-takers, such as Denison, Ostemberg, and Shelby may be requested. When carrying out the job, the required depth is reached by joining additional sections of auger.

**Wire-line** core-boring uses double core barrels in which the internal tube, together with the sample in question, may be brought back to the surface by means of a steel cable raised by an auxiliary winch installed onboard the rig. This eliminates the need to assemble and dismantle the masts, thus making the process more rapid, efficient and economical. There are various international nomenclature systems for the different diameters, originating from the leading manufacturers, (series Q, series K).

When samples are required from weak or unstable soils, the Geobor series of triple-tube core-barrels are used.

#### **Geophysical investigations**

It's a method that measures onsite the longitudinal and transverse seismic wave speeds in order to identify the deformability parameters. The required values are obtained by measuring the time taken for the seismic impulses to travel from an emitter to a receiver placed inside the probe cavity and encased in the appropriate tubing.

The main common feature of the various core barrels, according to the nature of the soil to be sampled, is the use of a core bit in hard alloy, with tungsten carbide inserts, or impregnated or mounted diamond.

Drilling using fluids, such as muds or biodegradable polymers, requires a higher rotation speed than that required by conventional drilling for micro-piles and tie rods, as shown in the diagram below:

In order to avoid a diamond dill bit shattering, owing to the weight of the drill string, the special rigs constructed by Soilmec and PSM are all equipped with a special hydraulic balancing system, thus eliminating this risk.

The rigs in the current PSM range designed for soil investigation, all of which can be identified by the letter G, consist of two units, with weights of 8 and 16 ton respectively, in either crawler or truck-mounted versions, with special 700 to 1000 rpm rotary heads, a fixed kinetic mechanism for precision work and a hydraulic piston push-pull system with extraction values between 9.5 tons and 19.5 tons, all with a wide range of accessories.

# Soil Investigation

#### MICRODRILLING

#### CONVENTIONAL EQUIPMENT FOR GEO-MECHANICAL AND GEO-TECHNICAL INVESTIGATION

	RODS • CASING • CORERS																						
			Ø hole			46		56		66		76	86		101		116		131			146	
	Simple Core mm			32		42		52		62	72		83		96		109			120			
ERS	T2		Core	mm		32		42		52		62	72		84								
COR	T6		Core	mm								57	67		79		9	93	108			123	
	T65 Core mm												72		[	56	101						
	T6 T	RX	Core	mm										76		90		90	103,5			118	
KERS	Øe	xt. m	m		ERG	1	01	N		86		101	116		≻	83	}	100	100 89			101	
LE TA	insp	ectio	on casir	ng	ERB!	ir	ох	INISC		PVC	I	PVC	PVC		HELB	galvan	ized	ized galvaniz		zed galvanized		galvanized	
SAMF	Ø and	l thickn	less of sar	nple taker	OST	88	,9/2	D		63/1,3	7	5/1,6	82/1,7		S		,5	100/1,5		1,5 88,9/2		101,6/2	
	Туре		42			50			70		76			90		114				1	40		
RODS	Thickness mm		kness mm 5			7			4		6,35			6,35		6,35		)	8,8				
	Weig	ght Ko	g/3 mt	13,	5		23,5			23,2		36			73		60				9	96	
	Ç	Øem	ım	4	4	5	4		64	7	74	84			98 11		113	113 12		28	28 143		
	STD	Øim	m	3	7	4	7		57	6	57		77		89		104		119			134	
NGS	١	weigh	t Kg/ml	3,	1	4	,4		5,2	6	i,2		6,9		10,6 1		12,6		14	14,3 15		15,5	
CASI	> (	Øem	ım	10	1		1	27				152			178 24		203 2		2	.44 273			
	HEAV	Øim	m	8	5		1	07				134			162		183		244			253	
	<u>،</u>	weigh	t Kg/ml	18	,4		2	8,9				131			33,4	3,4		5	57,8			64,8	
ßS	x Type AQ BQ			Ν	Q		Н	HQ		PQ			SQ		ຸ								
ORE	ROD	os ø	e mm		44,5			55,6			69	),9		88,	,9		114,3			139,7		9,7	
INE	RODS Ø i mm			34,9		46				60,3			77,8			103,2			125,4		5,4		
IRE L	HOL	.EØr	nm		48			60			75	5,8		96	6		1	12,6			14	-6	
Ň	CORE Ø mm		<b>CORE Ø mm</b> 27			36,5			47,6			63,5			85			107					





## **PSM-8G**

#### **SOIL INVESTIGATION**

The PSM-8G hydraulic drilling rig has been designed and built specifically for geognostic use. The high rotation speed of the hydraulic rotary allows continuous conventional core drilling both with hard alloy crowns and diamond crowns. Furthermore, it is suitable for wire-line core drilling down to a depth of 320 m.

The wide section mast with fixed kinematic mechanism houses a cylinder pull-push system for precision core drilling. Furthermore, the drilling rig has specific pressure gauges on the control panel for balancing the hydraulic drilling batteries to protect the diamond crowns.

#### Main features:

- Rotary head with 6-speed transmission and a maximum speed of 832 rpm.
- Fixed kinematic mechanism with +/- 13° mast inclination
- Extraction capacity: 9800 kg
- Hydraulic balancing

#### **Optional:**

- Triplex mud pump 185 L/45 bar
- Wire-line winch capacity 320 m Thrust block with pistons for inclined drilling
- Jet-grouting kit: 12 m treatment

Engine		DEUTZ TCD 2012 L04
Power	kW	103
Rated power	kW	85
Hydraulic System		
Main numn	l/min	140
Service numn	1/11111 1/min	71 + 76 + 29 + 23
	1/11111	71++0+23+23
Rotary		HR-9 coring
Max torque	daNm@rpm	916
Rotation speed	rpm	0 - 832
Mast feed/hoist system		
Standard cradle stroke	mm	3750
Rod lenght	mm	3000
Max hoist force	kN	98
Max feed force	kN	73
Max speed (slow/fast)	rpm	11 (14) - 32 (44)
Clamp & Breaker		
Clamping range	mm	60-260
Max clamping force	kN	11
Max breaking torque	daNm	3600
Service winch		
Max line pull 1st laver	kN	15
Rope diameter	mm	10
Wire line winch (entional)		
		220
Drum capacity Bono diameter	m	320 F
kope diameter	IIIII	5
Mud pump		
Max delivery	l/min	185
Max pressure	bar	45
Undercarriage		
Track shoe width	mm	300
Overall lenght	mm	2474
Overall width	mm	1900
Travelling speed	km/h	2,36
Weight		
Total weight	ka	8200 ÷ 9000
Average pressure on ground	MPa	0.063



## SOIL INVESTIGATION



## **PSM-16G**

#### **SOIL INVESTIGATION**

Specific equipment for Soil Investigation, designed for deep core drilling.

The high pull/push values and the high hydraulic power installed lets you use fast rotary speeds (over 1000 rpm) for conventional and wire-line diamond core drilling to great depths.

#### Main features:

- Rotary head with 6-speed transmission (maximum speed: 1000 rpm)
- Fixed kinematic mechanism
- Extraction capacity: 19500 kg
- Hydraulic balancing

#### **Optional devices:**

- Triplex mud pumps 185/45 bar
- Wire-line winch, 800 m rope capacityThrust block with pistons for inclined drilling
- Jet-grouting kit
- Double rotary

Engine		DEUTZ TCD 2013 L06 2V
Power	kW	200
Rated power	kW	176@1900 rpm
Hydraulic System		
Main numn	1/min	200
Sorvico numn	1/11111 1/min	200 142 - (64 - 44 - 22)
Service pullip	1/11111	142+(04+44+22)
Rotary		HR-10 coring
Max torque	daNm@rpm	1024
Rotation speed	rpm	1000
Mast food/baist system		
Standard gradle streke	mm	4000
Pod longht	mm	2000 (6000)
Max hoist force	LN	105
Max field force	kN	130
Max speed (slow/fast)	rnm	0 14 / 0 58
	ipin	0,117,0,00
Clamp & Breaker		
Clamping range	mm	60-320
Max clamping force	kN	3,4
Max breaking torque	daNm	8,6
Service winch		
Max line pull 1st laver	kN	30
Rope diameter	mm	14
Wire line winch (entional)		
wire-line winch (optional)		
Drum capacity	m	800
Rope diameter	mm	6
Triplex mud pump (optional)		
Max deliverv	l/min	185
Max pressure	bar	45
Undercarriage	100 100	400
Irack shoe width	mm	400
Overall width	mm	2700
	km/h	2500
navening speed	NI(1/11	د <sub>ا</sub> ع
Weight		
Total weight	kg	15000 - 17000
Average pressure on ground	MPa	0,07



**SOIL INVESTIGATION** 



## Transport conditions



## STM-8G

#### **SOIL INVESTIGATION**

Specific equipment for Soil Investigation, designed for deep core drilling, truck-mounted (preferability to Mercedes or lveco trucks).

The high pull/push values and the high hydraulic power installed lets you use fast rotary speeds for conventional and wire-line diamond core drilling to great depths.

#### Main features:

- Rotary head with 6-speed transmission and a maximum speed of 832 rpm.
- Fixed kinematic mechanism with +/- 13° mast inclination
- Extraction capacity: 9800 kg
- Hydraulic balancing
- Mast stroke: 7200 (x 6000 mm rods)

#### **Optional devices:**

- Triplex mud pump 185 l/45 bar
- Wire-line winch, 320 m capacity
- Thrust block with pistons for inclined drilling
- Special rotary heads for water well
- PTO air compressor

Engine		DEUTZ TCD 2012 L04
Power	kW	103@2400 rpm
Rated power	kW	85@1900rpm
Hydraulic System		
Main numn	l/min	1/0
Service numn	l/min	71+46+29+23
		, 1110123123
Rotary		
Max torque	daNm@rpm	916
Rotation speed	rpm	0-832
Mast feed/hoist system		
Standard cradle stroke	mm	3750 / 7200
Rod lenght	mm	3000
Max hoist force	kN	98
Max feed force	kN	73
Max speed (slow/fast)	rpm	0-17 / 35
Clamp & Breaker		
Clamping range	mm	60-260
Max clamping force	kN	100
Max breaking torque	daNm	3000
Service winch		
May line null 1st laver	٧N	15
Rope diameter	mm	10
wire-line winch (optional)		222
Drum capacity	m	320
Rope diameter	mm	5
Triplex mud pump (optional)		
Max delivery	l/min	185
Max pressure	bar	45
Weight		
Total weight*	ka	8200
	ĸy	0200

# STM-8G

## SOIL INVESTIGATION

#### Available mast stroke 7200 mm





## **STM-16G**

#### **SOIL INVESTIGATION**

Specific equipment for Soil Investigation, designed for deep core drilling, truck-mounted.

The high pull/push values and the high hydraulic power installed lets you use fast rotary speeds (over 1000 rpm) for conventional and wire-line diamond core drilling to great depths.

#### Main features:

- Rotary head with 6-speed transmission and a maximum speed of 1000 rpm
- Fixed kinematic mechanism with +/- 13° mast inclination
- Extraction capacity: 9800 kg
- Hydraulic balancing
- Mast stroke: 7200 (x 6000 mm rods)

#### **Optional devices:**

- Triplex mud pump 185 l/45 bar Wire-line winch, 800 m capacity
- Thrust block with pistons for inclined drilling
- Double rotary
- Special rotary head for water well application
- PTO air compressor for water well application

Engine		DEUTZ TCD 2013 L06 2V
Power	kW	200
Rated power	kW	176@1900 rpm
Hydraulic System		
Main numn	l/min	280
Service pump	l/min	142+64+44+22
Potory		
Notal y	de Nes Orrers	
Max torque Potation speed	daivm@rpm	1024
Kotation speed	трш	1000
Mast feed/hoist system		
Standard cradle stroke	mm	7110 / 3900
Rod lenght	mm	6000 / 3000
Max hoist force	kN	195
Max feed force	KN	130
Max speed (slow/tast)	rpm	12,6 - 51,6
Clamp & Breaker		
Clamping range	mm	60-320
Max clamping force	kN	23,7
Max breaking torque	daNm	11500
Service winch		
Max line pull 1st laver	kN	30
Rope diameter	mm	14
Wire-line winch (optional)		
Drum capacity	m	800
Rope diameter	mm	6
Triplex mud pump (optional)		
Max delivery	l/min	185
Max pressure	bar	45
Weight		
Total weight	ka	15000 / 17000
iotai iroigitt	Ng	15000717000

# STM-16G

### **SOIL INVESTIGATION**





#### MICRODRILLING

#### Method

Nowadays, the increasing need and demand of transferring a series of infrastructures to the underground has brought about an impressive rise in the numbers of tunnels to be constructed, regardless of the nature of the soil to be penetrated. The excavation of tunnels in loose soils, in presence of unstable formations or in presence of soils prone to landslide, requires the use of preventive consolidation of the arch and, if needed, of the walls and invert before the final lining is completed.

This has created a scenario of constant developing of technologies and machinery able to tackle any kind of situations.

The final aim is to reach the tunnel stability before the excavation through soil consolidation, avoiding expensive temporary supporting devices.

The Trevi Group has designed and successfully applied a tunnel consolidation technology known as RPUM (Reinforced Protective Umbrella System). The method finds its way in those tunnels with an unstable or short term stable core face condition. The technology envisages in the installation of a series of sub-horizontal elements aiming at consolidating the soil beyond the face of the tunnel before carrying out safely and speedily the excavation under the protection of the arch-like shell by using specially designed forepiling machinery.

Once such an operation is completed, a quite popular one especially in Europe, the tunnel is excavated usually in two stages (top heading and bench) or full face opening, under the protection provided by the consolidation and by installing a temporary lining consisting of steel ribs and shotcrete.



The length of each excavation step will be few meters shorter than the length of the protective umbrella forepiles, so as to allow an overlapping with the following series of forepiles.

As might be understood, the above mentioned operations require pretty long execution times.

In order to avoid interruptions and delays in the working cycle, the operations must be performed to an extremely exact time schedule. That means the consolidation tasks must be completed in the shortest possible time and at a constant rate.

The technological development has therefore pursued two major ways:

- The study and design of the right equipment able to efficiently operate in confined spaces, to be quickly set up in the required drilling position and finally able to execute longer and longer sub-horizontal consolidation in one single stage, thus dramatically reducing the cycle time.
- Design of the most suitable consolidation grout treatment for stabilizing the excavation and featured by mechanical strength to allow for the excavation and to reduce the number of supporting ribs to be installed.

Model	<b>Max (rated) power installed</b> <i>kW</i>	Working radius at 0° mm	<b>Max extension height a 0°</b> mm	Weight t
ST-15	92 (85) 90 electric	1880 ÷ 2550	4570	12,5
ST-20	129 (116) 90 electric	1700 ÷ 4696	6196	21
ST-30	153 (143) 90 electric	1528 ÷ 5037	6787	33
PST-60	155 (135) <i>118 electric</i>	3700 ÷ 6500	10700	64 - 66
ST-120	164 (135) 90 electric x 2	3600 ÷ 6600	10200	115

#### Equipment

#### MICRODRILLING

#### **R.P.U.M.** Techniques

RPUM technique is the result of such developments and the Execution Phases involves the installation of either suitable reinforcing steel pipes or of consolidated columns by using the JET GROUTING system:



The method consists in the installation of manchette-type steel pipes acting as reinforcement support for the next installation of the steel ribs. At the same time they are also used as grouting pipes thus forming a continuous canopy of consolidated soil.



**1. Drilling phase:** The drilling can be performed either by rotation or rotopercussion (TUBEX-ODEX-like) In the first case, the drilling string itself, fitted with a drag bit at its end, is left in place whilst in the roto-percussion is the casing to be left in place.

In both cases, the drilling string or the casing, acting as reinforcing steel of the consolidation treatment, are fitted with special non-return valves , which are built within the wall thickness of the steel pipes and are such as not to suffer damages during the penetration of the soil.



#### MICRODRILLING

- 2. Grouting phase: basically we have two grouting techniques:
  - a. The single valve injection technique by means of which each individual valve is pressurized using a double packer placed across to each valve.
  - b. The one -shot technique for each individual forepile by using a packer placed at the top of the pipe







#### MICRODRILLING

#### **Jet Grouting**

**JET GROUTING** method is also widely employed today thanks to its suitability in a variety of soil ranging from gravel to clay but especially in very difficult conditions where both weak soils and thin overburden are there. In fine soils, the column has a static function while where there is water inflow it works as a barrier against the water.

The execution phase of the so called Trevi Reinforced Jet Grouting in Progress (normally T1 single fluid is suggested) is the following:

- Drilling is carried out by using a rod string fitted with a monitor and a drilling tool, either by rotation or roto-percussion.
- During the drilling phase, the inside fluid escapes from the tool tip, easing therefore the soil penetration and keeping the drilling tool blades clean.
- When the drilling is over , the jet is diverted by closing the bottom valve and the grout escapes at high speed through the side nozzles, disaggregating and mixing the soil with the grout and thus creating the consolidated column. During this phase the drilling string is rotated and withdrawn at a pre-set rate.
- The peculiarity of this system is that the reinforcing steel pipe is installed together with the placing of the jet grouting column. The jetting string and the casing rotates in opposite senses.
- The jetting string itself, fitted with the monitor, is located inside while about 20 cm back the reinforcement pipe is fitted.
- The treatment is performed by driving both the rod and the casing simultaneously and performing the jetting during the penetration phase. The space between the rods and the pipe allows the jetting spoil to escape. On completion of the drilling/treatment, the jetting string is extracted from the casing which remains in place to serve as reinforcement.
- This type of consolidation obviously requires the use of a double head.
- The grouts used are generally binary Cement/Water following a ratio of 0.8 to 1.3 with , in case, the use of admixtures. The High Pressure Jetting is carried out by suitable High Pressure Pumps.

Soilmec Tunneling rigs have been specially designed and adapted to complete this type of work in the most efficient and effective way where speed and precision are demanded.

In addition such a process allows easier and more cost effective treatment of either soft soil or fractured and soft rock.

Today Soilmec can offer a wide range of equipment capable of covering radius of consolidations from 1500 mm to 6800 mm at 0° thus applicable both in large tunnelling sections for High Speed Railways and highways projects and in those tunnels thought for the city underground systems which consists normally of small sections.

#### See the tunnelling rigs in jet grouting version pag. 22



#### **TUNNELLING RIGS**

The market increasing demand for tunnelling equipment able to consolidate the weak/unstable soil ahead of the tunnel face before the excavation has brought Soilmec to again widen and complete its range including a very compact tunnelling machine named ST-15.

Especially designed for easily enter and work in narrow spaces keeping all the main features and high performances of the larger machines for tunnelling consolidation. Brilliantly designed to be exceptionally valuable for Metro tunnels, Service tunnels, etc. and yet in all that cases in which the machine needs to be often and quickly moved from one narrow place to another and lowered down in very narrow shafts.

#### Main features:

- Overall width: 2100 mm
- Overall length: 2780 mm
- Front and rear fixed telescopic rams
- Front and rear hydraulic slewing rings
- Diesel engine and electric motor interchangeable
- Rotary head achieving a max. torque of 1207 daNm
- Jet grouting optional by mast extension
- Class of the machine: 12 ton

Performances				
Max height of consolidation treatment a 0°	mm	4570		
Max height of consolidation treatment a 5°	mm	5157		
Radius of consolidation treatment a 0° (min/max)	mm	1880	2550	
Radius of consolidation treatment a 5° (min/max)	mm	2131 (2712)	3137 (3387)	
Height from working level of slew ring rotation axis	mm	1020-	2020	
Hoist and food system		Tuppol	Tuppel let	
Food stroke	mm		11250	
Max hoist force		52	F2	
Max food force		52	52	
Max reed force	rpm	JZ 25 7	JZ 25 7	
Red diameter	ipin mm	ZJ-1	25-1	
Rod dialifeter	111111			
Diesel engine		DEUTZ TCD	2012 L04	
Max power	kW	92		
Rated power	kW	85		
Electric motor			50 47 280/660 1/	
Dower				
Power	KVV	90 @ 12	1011 CO	
Hydraulic System*				
Main pump (variable displacement axial pumps)	l/min	221		
Auxiliary pump (gear pumps)	l/min	54+24+40+27		
Rotary		10	07	
Max torque	dainm	1207		
Drilling speed	rpm	221		
Clamp & hydraulic joint breaker				
Size	mm	60-225		
Max clamping force	kN	159		
Max breaking torgue	daNm	3830		
Undercarriage		25	· •	
	mm	350		
	mm	2544		
Overall width		11111 Z100		
navening speed	KIII/II	km/n 2,4		
Weight				
Total weight	ka	kg 12250 (standard) 12750 (iet)		
Average pressure on ground	MPa	0,09		

\* double idraulic system (diesel+electric)

TUNNELLING RIGS

## Working condition Std





## Working condition with extension



Consolida <sub>alfa</sub> (°)	tion Height H max (m)	H min (m)
0	4570	2900
1	4706	2933
2	4841	2965
3	4976	2997
4	5106	3035
5	5157	3151
6	5207	3267
7	5258	3383
8	5308	3499
9	5357	3616
10	5407	3732
11	5456	3849
12	5504	3966
13	5553	4083
14	5600	4201
15	5648	4319

Radius of Consolidation			
alfa (°)	R max (m)	R min (m)	
0	2550	1880	
1	2686	1913	
2	2821	1945	
3	2956	1977	
4	3092	2015	
5	3137	2131	
6	3187	2247	
7	3238	2363	
8	3288	2479	
9	3337	2596	
10	3387	2712	
11	3436	2829	
12	3484	2946	
13	3533	3063	
14	3580	3181	
15	3628	3299	





### TUNNELLING RIGS






















## ROTARY EQUIPMENT FOR TUNNELLING



#### TUNNELLING RIGS

The ST-20 tunnelling rig is ideal for sub-horizontal consolidation in tunnels with a work radius of between 1512 mm and 4696 mm (with the drilling mast horizontal at 0°). The useful stroke of the rotary allows treatments of up to 14 m (16 with the optional extension).

The drilling mast can be folded in at both ends, reducing the overall dimensions, to make the rig easier to transport both underground and on the road at the end of the job.

The machine has two motors (diesel and electric) of a suitable size for each single motor to perform all the drilling, traversing and positioning operations of the crawler.

#### The following drilling techniques can be applied using the ST-20:

- Rotation (with or without casing)
- Rotopercussion by means of Top Hammer (with or without casing)
- Rotopercussion by means of Down the Hole Hammer (with Tubex, Odex or Simmetrix superjews system)

Performances				
Max height of consolidation treatment a 0°	mm	6200		
Max height of consolidation treatment a $5^{\circ}$	mm	6470		
Radius of consolidation treatment a 0° (min/max)	mm	1700	4696	
Radius of consolidation treatment a 5° (min/max)	mm	2100-2850	4050	
Height from working lovel of slow ring rotation axis	mm	2100-2000 1500 (fivo	4) 400	
Height from working level of slew fing fotation axis	111111	1300 (139	J)	
Hoist and feed system				
Feed stroke	mm	14200	16000	
Max hoist force	kΝ	67	67	
Max feed force	kN	67	67	
Max speed (feed/hoist)	rpm	32-9	-	
Rod diameter	mm	114	90	
		117	50	
Diesel engine		DEUTZ 2013 L	04 2V	
Max power	kW	129		
Rated power	kW	116@1900	rpm	
Electric motor			·	
Power	kW	90		
Hydraulic System				
Main numn (variable displacement axial numns)	l/min	150		
Auxiliary numn (dear numns)	l/min	86+86+3/+(22+22+12)		
	1/11111	80+80+34+(22+22+12)		
Rotary				
Max torque	daNm	1350@48 rpm		
Drilling speed	rpm	460		
Clamp & bydraulic joint broaker				
clamp & hydraulic joint breaker		CO 2CO		
Size	mm	60-260	440	
Max clamping force	KIN	159	110	
Max breaking torque	daNm	3830	3600	
Rod carousel (optional)				
Rod diameter	mm	114	90	
Rod lenght n° rod		13	15	
		15	15	
Undercarriage				
Track shoe width	mm	400		
Overall lenght	mm	3280		
Overall width	mm	2490		
Travelling speed	km/h	1,63		
Weight				
Total weight	ka	21000		
Average pressure on ground	MPa	2 1000 0 100		
Average pressure on ground	ivii a	0,100		

## TUNNELLING RIGS















#### TUNNELLING RIGS

The ST-30 tunnelling rig is suitable for the sub-horizontal consolidation of medium-size tunnels, with a drilling radius of between 1528 mm and 5037 mm (drilling mast inclination 0°) and max. heading stroke heights of 6767 mm.

It can be used in tunnels with a greater section, using the so-called "half-section" method with the first phase envisaging the reinforcement of the upper heading, and the following excavation of the invert in the second phase. The machine has two motors (diesel and electric) of a suitable size for each single motor to perform all the drilling, traversing and positioning operations of the crawler.

#### The following drilling techniques can be applied using the ST-30:

- Rotation (with or without casing)
- Rotopercussion by means of Top Hammer (with or without casing)
- Rotopercussion by means of Down the Hole Hammer (with Tubex, Odex or Simmetrix superjews system)

Performances				
Max height of consolidation treatment a 0 $^\circ$	mm	6787		
Max height of consolidation treatment a 5°	mm	7197		
Radius of consolidation treatment a 0° (min/max)	mm	1528	5037	
Radius of consolidation treatment a 5° (min/max)	mm	2550	5447	
Height from working level of slew ring rotation axis	mm	1750		
Hoist and feed system		Horizontal	Vertical	
Feed stroke	mm	13000/14000	7000	
Max hoist force	kN	84		
Max feed force	kN	84		
Max speed (feed/hoist)	rpm	0-30		
Diesel engine		CUMMINS OSB	Tier 3	
Max power	kW	153		
Rated power	kW	143		
Electric motor		1.15		
Power	KVV	90		
Hydraulic System*				
Main pump (variable displacement axial pumps)	l/min	297		
Auxiliary pump (gear pumps)	l/min	55-25		
Rotary				
Max torgue	daNm	1350		
Drilling speed	rpm	461		
Clamp & hydraulic joint breaker				
Size	mm	60-260		
Max clamping force	kN	159		
Max breaking torque	daNm	3830		
Undercarriage				
Track shoe width	mm	600		
Overall lenght	mm	37/0		
Overall width	mm	2300 / 3400		
Travelling speed	km/h	1,5		
Weight		Horizontal	Vertical	
Total weight	ka	30000/32000	28000	
Average pressure on ground	MPa	0,09		

\* double idraulic system (diesel+electric)





### **TUNNELLING RIGS**

### Working radius at 0 $^\circ$



Working radius at  $5^{\circ}$ 





### Working radius at 23°





## TUNNELLING RIGS















### **TUNNELLING RIGS**











## **PST-60**

#### **TUNNELLING RIGS**

The tunnelling rig project was developed to meet the growing need for sub-horizontal consolidation in large-section tunnels using single-boom equipment working with the full section method as an excellent alternative to the double-boom type system traditionally used for this type of job.

The equipment, with an overall weight of between 62 and 65 tonnes is very flexible and fast to use, also in relation to the importance of the treatments to perform. To reach the maximum heading stroke points with respect to ground level, a special system of thrust blocks and sliding blocks was designed to reach these points in total safety. The machine has a mast for 19000 mm treatments in one pass and 24000 m treatments with matching chuck and optional extensions.

The maximum extension height at 0° with respect to ground level is 10700 mm.

The variability of the height of the thrust block axis of rotation from 850 mm to 4250 mm combined with the column extension allows a work radius of from 3700 mm to 6500 mm. Tunnel lining is over 180°.

Fitted with two motors (diesel and electric) for both drilling and traversing, guaranteeing performance also in case of a breakdown of one of the two units.

#### The following drilling techniques can be applied using the PST-60:

- Rotation (with or without casing)
- Rotopercussion by means of Top Hammer (with or without casing)
- Rotopercussion by means of Down the Hole Hammer (with Tubex, Odex or Simmetrix superjews system)

Performances			
Max height of consolidation treatment a 0°	mm	20	
Max height of consolidation treatment a 5°	mm	10700	
Radius of consolidation treatment a 0° (min/max)	mm	3675	6475
Radius of consolidation treatment a 5° (min/max)	mm	3675	7147
Height from working level of slew ring rotation axis	mm	850-4262	
Helet and final materia			
Hoist and feed system		10000 (24000	1113
Feed stroke	mm	19000 (24000 option	nal kit)
Max hoist force	KN	/0	
Max feed force	KN	/0	
Max speed (feed/hoist)	rpm	26	
Diesel engine		DEUTZ 2012 LO	6
Max power	kW	155	
Rated power	kW	135	
		155	
Electric motor		SIEMENS 4 POLS 50 H	łz 380V
Power	kW	110	
Hydraulic System			
Main numn (variable displacement avial numna)	l/main	250	
Auxiliary rump (variable displacement axial pumps)		ZDU F0 + 00 + 20 + 2	
Auxiliary pump (gear pumps)	1/11111	50+90+30X2	
Rotary		HR-17	
Max torgue	daNm	1747	
Drilling speed	rpm	295	
Clamp & hyuraulic joint breaker			
Size	mm	60-250	
Max clamping force	KN	159	
Max breaking torque	daNm	3830	
Rod carousel (optional)			
Rod diameter	mm	114-90	
Rod lenght n° rod		18000x1	
Nou lenght in Tou		1000001	
Undercarriage			
Track shoe width	mm	600	
Overall lenght	mm	4510	
Overall width	mm	2500 (3700)	
Travelling speed	km/h	1,5	
Weight			
Total weight	ka	62000/65000	
Average pressure on ground	MPa	02000/03000	
	IVII U	0, 12	

# **PST-60**

### **TUNNELLING RIGS**









#### **TUNNELLING RIGS**

The ST-120 tunnelling rig is the top of the Soilmec tunnelling range.

Designed for the consolidation of large section tunnels it can be used for treatments up to a maximum of 21000 mm in one pass and 24000 mm with matching chuck. Heights of 10100 mm can be reached at the heading with the arms perfectly horizontal at 0°.

The main feature of the ST120 positioner is the geometry of the two cradles that house the system of sliding blocks and telescopic arms, letting you work far from the face to consolidate (12000 mm) guaranteeing the greatest safety in operations underground. Furthermore, each of the single drilling arms is fully independent, driven by two separated power and remote control units.

The weight of the rig in operational layout, depending on the optional devices fitted and the configuration used, is between 110 and 120 tonnes.

#### The following drilling techniques can be applied using the ST-120:

- Rotation (with or without casing)
- Rotopercussion by means of Top Hammer (with or without casing)
- Rotopercussion by means of Down the Hole Hammer (with Tubex system or without casing)

Derformances		
Performances		40420
Max height of consolidation treatment a 0°	mm	10120
Max height of consolidation treatment a 5°	mm	10736
Radius of consolidation treatment a 0° (min/max)	mm	3600 6600
Radius of consolidation treatment a 5° (min/max)	mm	5266 7216
Height from working level of slew ring rotation axis	mm	1000-3500
Hoist and feed system		
Feed stroke	mm	16000-18000-21000
Rod lenght	mm	12000
Max hoist force	kN	8400
Max feed force	kN	8400
Max speed (feed/hoist)	rpm	30-5
Diesel engine		CUMMINS 6 CTA A 8.3
Max power	kW	164
Rated power	kW	135
Electric motor		
Electric motor		SIEMENS 4 PULS 50 HZ
Power	kW	90
Hydraulic System		
Main nume (cariable dimbron enterial numer)	l (main	
wain pump (variable displacement axial pumps)	i/min	(214+214)+142/2X(158+158)+2X158
Auxiliary pump (gear pumps)	I/min	4772X(46+24)
Rotary		HR-14
Max torque	daNm	1363
Drilling speed	rnm	/1505
Drining speed	трпі	101
Clamp & hydraulic joint breaker		
Size	mm	60-225
Max clamping force	kN	159
Max breaking torque	daNm	3830
3		
Rod carousel (optional)		
Rod diameter	mm	114
Rod lenght n° rod	m	18
Undercarriage		
Irack shoe width	mm	800
Overall lenght	mm	5041
Overall width	mm	3900
Travelling speed	km/h	1,36
Weight		
Total weight	ka	110000 / 120000
	KY MDo	0.17
Average pressure on ground	IVIPa	0.17

### TUNNELLING RIGS

Working configuration 21 m









### **Transport conditions**



TUNNELLING RIGS





## Tilting configurations





### **TUNNELLING RIGS**





TUNNELLING RIGS



# **Special Applications**

#### **PRE-BORE / CFA**

The company's widespread penetration of international markets, has made it possible to identify and meet the special requirements that emerge from individual markets.

The company has developed rigs that not only meet the demands of industrial standardisation, but are also able to respond to the individual requirements of our customers, for higher performance for some types of operating processes peculiar to their own countries.

#### PRE-BORE

In some European countries, the use of driven pre-stressed piles is particularly highly-developed and widespread, giving rise to the pre-bore technique, the result of recent technology, making it possible to improve the operating cycle on sites of great complexity.

Primary bores of 450-510-600mm, using lightweight, fast-moving equipment, are drilled to a depth of 6/8 metres, to facilitate the subsequent operation of the heavier rigs equipped with vibrating drivers that guarantee better placement in the cavity. The increase in speed has considerably improved operating cycles.

#### Low-headroom CFA

Soilmec is the overall market leader in the development of the hydraulic rotary rig for continuous flight auger (CFA) drilling. Work on the CFA technology has been going on within the Trevi Group since 1970, in England at Soilmec UK, and this has subsequently been exported to other countries. This method is ideal for laying large-diameter piles (max 1000 mm diam.) in soils with a high sand, silt or clay content, and it is based on the principle of jetting in the concrete as the resulting material is being extracted, by keeping the cavity under pressure.

The minimum weight of the rigs is 40 tons and they use long masts in order to perform the jet grouting in a single pass.

The growing demand for this type of pile to be used for rebuilding existing structures and in the construction of industrial buildings, has led to the development of the low-headroom CFA, with the jet grouting proceeding in progressive sections using lightweight equipment (max. 18 tons), giving complete onsite flexibility.



## SM-14PB/CFA

#### **SPECIAL APPLICATIONS**

The SM-14, the most widely used model in the range, is equipped with a special rotary head that is capable of reaching a torque of 2500 daNm, ideal for the auger drilling required for areas in which plastic clays are present. It also has a special 600mm diameter auger guidance system and a universal joint, to guarantee that the work is carried out with precision, something highly unusual in a rig of this size.

- Concrete injection kit with rotary and 4" injection head
- 600 mm bottom auger guide



Undercarriage with oscillating tracks					
Track shoe width	mm	400			
Overall lenght	mm	3062			
Overall width	mm		230	00	
Travelling speed	km/h		2,	7	
Average ground pressure	MPa		, 0.0	)7	
5 5 1			.,.		
Diesel engine					
Make and model		CUMN	AINS QS	B 4.5 - Ti	er III
Max (rated) diesel engine power	kW	123	(119)@	🦻 2000 rp	m
Flostvic motor (or request)					
Electric motor (on request)					
Make and model		SIEN	MENS 4 I	POLS 50 H	lz
Rated power	kW (BHp)	90	(119)@	1485 rpn	n
Hydraulic System					
OII tank capacity	I	400			
Rotary head		HR-25			
Gear box type		variable			
Max nominal torquo	daNm	25/17			
Max holling speed	uaiviii	2547			
Imper passage	rpm	0-52			
inner passage	[[]][]	140			
Mast hoist & feed system		Standard		(	Optional
Feed type		Cylinder		Ge	ar motor
Feed stroke	mm	2100-4000	)		7000
Max hoist pull	daN	8900			8700
Max feed force	daN	4500			8700
Max speed (fast operation)	rnm	28			28
	ipin	20			20
Clamp & Breaker		Standard	Optio	onal	Auger
Clamping range	mm	50-315	50-3	360	600
Max clamping force	kN	266	26	56	-
Max breaking torgue	daNm	5060 5060 -			-
Comitos winch					
Service winch					
Max line pull (1st layer)	kN		20	0	
Max rope speed (4st or 5st layer)	m/min		60	0	
Rope diameter	mm		1(	0	

# SM-16PB/CFA

#### **SPECIAL APPLICATIONS**

The PSM-16 was studied and designed specifically to be extremely compact, with an impressive power output, to use a double rotary head with a fixed kinematic mechanism and a mast positioned with a 19.5 ton hydraulic piston. It is particularly suitable for transformation and use with the most demanding CFA technology.

This led to the PSM-16 CFA with a 4500 daNm rotary head and guide system for 600 mm diameter augers. With special accessories it can be used for auger drilling with 450-500 mm diameter casings.

The PSM-16PB is based on the PSM-16GT drilling rig (designed for geothermal operations).

The Pre-Bore application envisages the use of a special mast with a maximum height of 25 m.

- Concrete injection kit with rotary and  $4^{\prime\prime}$  injection head

- 660 mm clamp with 600 mm guide

Engine				
Model	kW	DEUTZ TCD 2	013 L06 2V	
Max power	kW	200 (272) @ 2400 rpm		
Hydraulic System				
Main pump and service pumps	l/min	28	0	
Max work pressure	MPa	28	3	
Rotary head		HR-	45	
Max torque (28 Mpa)	daNm@rnm	/5(	)()	
Retation speed	rpm	4.50	00	
Rotation speed	ihiii	0-11	00	
Mast feed/hoist system				
Standard cradle stroke	mm	2500	7000	
Max hoist force	daN	19500	19500	
Max feed force	daN	13000	13000	
Max speed (slow/fast)	m/min	0.14/0.58		
Clamp & Proakor				
		220 540 /		
Clamping range	mm	320 - 510 (660 auger)		
Max clamping force	daN	24		
Max breaking torque	daNm	12000		
Service winch				
Max line pull 1st laver	daN	200	00	
Rope max speed in 4th layer	m/min	43	3	
Rope diameter	mm	14	1	
Undercarriage			-	
Shoe	mm	40	0	
Overall lenght	mm	276	50	
Overall width	mm	230	00	
Max speed	km/h	2,3	3	
Weight				
Total weight	ka	15000-	17000	
Average pressure on ground	MPa	10001	17000	
nierage pressure on ground	ivii u	0,0		

# **GEOTHERMAL ENERGY**

#### MICRODRILLING

Geothermal energy is a natural resource. In fact, the earth contains an inexhaustible supply of heat. As the depth increases, so does the temperature thanks to the geothermal energy coming from the earth's core and rising towards the surface. What's more the earth's crust absorbs over 40% of solar energy.

This makes geothermal energy inexhaustible, constantly available, and a free and renewable source of energy; homes, offices, shopping areas, and whole residential complexes can be heated and air-conditioned at a much lower cost than when using traditional energy sources.

#### **Applications**

The extraction of heat from the ground and the distribution of the same to heat and air-condition environments can be done using various types of plants.

Applications of this type, called "low enthalpy", are most often used in residential buildings and commercial areas (Ecoconstruction).

The drilling depth to install the "Ground Source Heat Pump (GSHP)" varies from 50 to 200 metres.

Model	twin rotary kNm	pull force kW	Max (rated) engine power kW	clamp & breaker kNm
PSM-8GT	upper 8 lower 16	98	129 (116)	60 - 260
PSM-16GT	upper 11 lower 32	195	200 (176)	60 - 320

The traversing system and the compact dimensions are the strong points of our machines, which can be equipped with:

- (BOP) automatic greasing
- Magnetic loading system for rods and casings
- Triple clamp and breaker
- Double rotary (or hammer at the head for rods and bottom rotary)
- Mud pump
- Rubber tracks



# **GEOTHERMAL ENERGY**

MICRODRILLING





## **PSM-8GT**

#### **GEOTHERMAL ENERGY**

The new PSM-8GT is a hydraulic drilling rig designed specifically for geothermal drilling.

The fixed kinematic mechanism, wide section mast, and the pull-push system with a 98 kN hydraulic cylinder means drilling deep, precise bores.

The rubber tracked undercarriage and low specific pressure on the ground make this machine ideal for operating in gardens and private courtyards, typical in this kind of application, reducing the impact of the site.

The drilling rig has a hydraulic clamp and breaker suitable for breaking drilling rods and an additional support for manoeuvres during feeding and recovery of the casings.

The drilling battery loading (rods and casings) is fast and safe thanks to a special winch system with magnetic lifting.

Engine			DEUTZ TCD 2013 L04 2V
Power		kW	129
Rated power		kW	116
Hydraulic System			
Main numn		l/min	273
Service pump		l/min	111 + (57+36+28)
Dauble veterre			
Double rotary		1 1 1 1	IK-816
Lower	Max torque	daNm	1663@26
	Rotation speed	rpm	816@53
Upper	Max torque	dainm	816@53
	Rotation speed	rpm	408@106
Mast feed/hoist sys	tem		
Standard cradle strol	ke	mm	3750
Rode lenght		mm	3000
Max hoist force		kN	98,1
Max feed force		kN	73,6
Clamp & Breaker			
Clamping range		mm	60-260
Max clamping force		daN	196
Max breaking torque	2	daNm	3500
Undorcarriago			
Track shop width		mm	400
Overall lenght		mm	400
Overall width		mm	2420
Travelling speed		km/h	2.5
			<u> </u>
weight			
Total weight		kg	9000
Average pressure on	ground	MPa	0,057

# PSM-8GT

**GEOTHERMAL ENERGY** 



### **Transport conditions**





## PSM-16GT

#### **GEOTHERMAL ENERGY**

The new project responds to the demand of geothermal systems drilling between 100 and 250 metres. The equipment's characteristics mean it can satisfy 70% of demand from the low-enthalpy geothermal sector. The compact drilling rig has a rubber tracked, 2300 mm-wide carriage and very low ground bearing pressure (0.65 Kg/cm2), thereby minimising damage to private property (gardens and courtyards) where domestic geothermal energy is used.

The drilling rig is equipped with fixed kinematic mechanism with a wide section mast, half-cylinder pull/push and a 19.5 ton pull capacity and 9.8 ton push power.

The rig is designed for rapid manoeuvring  $(0.2 \div 0.6 \text{ m/sec})$  and has a 200 kW, 2400 rpm diesel engine adapted to power the double rotary (upper 1100 daNm - bottom 3200 daNm), triple clamp and magnetic loading system to simultaneously manoeuvre rods/casings.

To keep weight to a minimum the drilling rig is not fitted with heavy and bulky casing/rod storage and is instead accompanied by an autonomous motorised rack system during operation.

Engine			DEUTZ TCD 2013 L06 2V
Power		kW	200
Rated power		kW	176
Hydraulic System			
Main numn		l/min	280
Service nump		l/min	142+(64+44+22)
		011111	1121(01111122)
Double rotary		1.1.1	
Lower	Max torque	daNm	3200
	Rotation speed	rpm	50
Upper	Max torque	dainm	1100
	Rotation speed	rpm	80
Mast feed/hoist sys	tem		
Standard cradle stro	ke	mm	4000
Rode lenght		mm	3000
Max hoist force		kN	195
Max feed force		kN	130
Max speed (slow/fas	t)	rpm	0,14 / 0,58
Clamp & Breaker			
Clamping range		mm	60-320
Max clamping force		daN	24
Max breaking torque	2	daNm	1200
Undercarriage			
Track shoe width		mm	400
Overall lenght		mm	2760
Overall width		mm	2300
Travelling speed		km/h	2,3
Weight			
Total weight		ka	15000-17000
Average pressure on	around	MPa	0.7
ge pressare on	<u>.</u>		<b>0</b> <i>1</i> .

# PSM-16GT

**GEOTHERMAL ENERGY** 



### **Geothermal Rack**





# **Vibrodrilling Technology**

### ROTARY

**VR Rotary - Vibrodrilling Technology** combines rotary drilling with driving that uses eccentric vibrating masses. Together these two energy sources can extend the drilling range of head and down-the-hole percussion.

The vibrorotary consists of a vibrator and rotary mechanically coupled to permit simultaneous operation. During normal rotation, the rotary provides torgue by rotating the drill string via the shank.

Vibrator start-up causes axial oscillation that moves the drill string within a predetermined amplitude.

The combined rotary and vibrating movement generate drill string motion that reduces the friction coefficient with the soil and produces a "slackening" effect which decreases drilling resistance. This facilitates penetration while cutting down on drilling time and the amount of push/pull required.

#### EQUIPMENT

The vibrator is fixed to the cradle through elastic connectors, which dampen vibration on the rest of the machine. The vibrating part is axially guided and connected to the bottom rotary via a mechanical connection known as a joint swivel.

The rotary (anchored to the same cradle as the vibrator) imparts torque and rotation via the shank.

A swivel is mounted on the end to allow for the addition of drilling fluids (air, water, polymers, muds and cement).

A diverter (ejection bell) is available when using double drill strings for the removal of drilling detritus that rises inside the casing.

The drill string and instruments have been specifically designed for use with this technology.

#### **TECHNOLOGY COMPARING**

VR Technology can ensure efficient feed and high productivity in all applications that use percussion.

Compared with similar technologies, VR offers the possibility of applying heavy force on drill strings in a continuous manner (through vibration) rather than in impulse, as is the case for head percussion or down-the-hole drilling.

The vibrating energy and centrifugal forces are higher than for similar traditional percussion systems.

In addition, the drill string can be vibrated during both feed and extraction, thus eliminating the risk that drill strings become stuck.

VD productivity therefore compares favourably with percussive systems and can be operated at depths of over 100 m.

#### ADVANTAGES

VR Technology can be used to perform single drilling or casing drilling with the circulation of fluids and maximises efficiency on soft soil layers (sand, gravel, rocks, general cover soil - OD drilling).

The technology can be used for both vertical and inclined drilling (stay rods and anchoring).

#### The main advantages are:

- Reduced friction between drill string and soil
- Decreased extraction pull required for stuck drill string
- Reduced torque required for drilling
- Reduced drilling time (compared to rotary drilling)
- Increased efficiency (compared to percussive systems)
- Reduced drill string wear as a result of continuous non-impact vibration
- Reduced noise emissions (compared to percussive systems)





Drilling cutting

Soft soil layers

ROTARY

Two models are available: VR-108 and VR-212

VD 108 is ideal for operation between 50-80 m with a drill string up to 2500 kg. VD 212 is recommended for operation over 100 m with a drill string up to 3500 kg.

VIBRO ROTARY SM-14		VR-108			VR-212	
Drilling performance						
Rod Diameter range	mm	76 - 22	4	76 -	224	
Operative rod weight	kg	2500		35	00	
Depth	m	80 (according to	soil type)	100 (accordin	ig to soil type)	
Drilling angle	0	0 - 90°		0 - 1	90°	
Hydr. exciter block						
Туре		HV-1		HV-2		
Frequency	Hz (rpm)	41 (2460) 57 (3400)		60 (3600) 53 (3180)		
Centrifugal force	kN	70	90	242	189	
Hydr. power	kW	38.5	47.6	50	44	
Max amplitude	mm	8.9	9.3	8.1	8.1	
Hydr. rotary head						
Туре		HD-800	G	HD-1	200V	
Hydr. power	kW	38.5		7	0	
Ranging torque	daNm	780 - 39	0	1270	- 302	
Max speed	rpm	80	80		21	
VD dimension	mm	1760x1065	x720	1050x62	20x1700	
VD total weight	ka	1250		1320		

We can also supply single or double cement injection swivels (single or double fluid), casings and rod drill strings ranging in diameter from D76 mm to D244 mm and specific tools for different soil types.



RODS	Single rod	Rod and Casing
	90	76 and 114
	101	90 and 133
	114	90 and 152
	133	114 and 178
	152	114 and 203
	178	133 and 203
	219	133 and 219



- 1. Double swivel for jet grouting
- 2. Double swivel for drilling fluids
- **3**. Single swivel for jet grouting

# **Modular options**

### ROTARY

The range of hydraulic rotary rigs is wide and complete enough to meet the most diverse drilling needs.

All the designs are based on the modular principle thus making it possible to fit the most suitable and most high performance rotary head to any of the SOILMEC/PSM rigs, taking into account the hydraulic power and the technology installed onboard the rig.

To achieve the best results for auger and tri-cone rotary drilling and for DTH hammers, different degrees of torque and drilling speed must be used, depending on the diameters required and the soil morphology.

Soilmec can offer:

- Variable rotaries, without gears, whose torque and rpm values can be selected by the operator in situ. These are the most universal machines, with a max. rpm of 221.
- Rotaries with manual gearing, with two or more three ratios, making it possible to work up to 429 rpm. These are identified by the letters G (gear variable).
- Geared rotaries designed for soil investigation. These are equipped with six ratios between 832 and 1000 rpm for operating with diamond core barrels. Identified by the word coring.

	PSM-8 PSM-8B	PSM-8G	SM-14	PSM-16G	PSM-20	SM-21	SM-30
HR-9 Coring							
HR-10 Coring							
HR-14 Coring							
HR-10 G							
HR-12							
HR-13 G							
HR-16 G							
HR-17 G							
HR-20							
HR-21 G							
HR-25							
HR-37							
HR-45							

# Modular options

ROTARY

HR-9 Coring		
Gearbox	type	6 gear box
Max torque	daNm	916
Speed	rpm	0-832
Inner rod passage	mm	90
HR-10 Coring		
Gearbox	type	6 gear box
Max torque	daNm	916
Speed	rpm	0-832
Inner rod passage	mm	90
HR-14 Coring		
Gearbox	type	6 gear box
Max torque	daNm	1300
Speed	rpm	0-1000
Inner rod passage	mm	90
HR-10 G		
Gearbox	type	4 gear box
Max torque	daNm	1024
Speed	rpm	0-381
Inner rod passage	mm	90
HR-12		
	type	variable
Max torque	daNm	1207
Speed	rpm	0-221
Inner rod passage	mm	114
HR-13 G		
Gearbox	type	6 gear box
Max torque	daNm	1290
Speed	rpm	0-429
inner rou passage	11111	114
HR-16 G		
Gearbox	type	4 gear box
Max torque	dainm	0.184
Inner rod passage	mm	90
		50
HK-17 G		1 marshau
Gearbox	daNm	4 gear box
Sneed	rpm	0-295
Inner rod passage	mm	90
HR-20		
	type	variable
Max torque	daNm	2025
Speed	rpm	0-179
Inner rod passage	mm	127
HR-21 G		
Gearbox	type	4 gear box
Max torque	daNm	2154
Speed	rpm	0-315
Inner rod passage	mm	127
HR-25		
	type	variable
Max torque	daNm	2047
Speed	rpm	0-52
Inner rod passage	mm	150
HR-37		
Gearbox	type	variable
Max torque	daNm	3659
Speed	rpm	0-12/
inner rou passage		140
HR-45		
Max taxaus	type	variable
Speed	dainm	4500
Inner rod passage	mm	1/10
inner rou pubbuge		

N.B. The indicated values are based on pressure 280 bar Different regulation are available please contact microdrilling department

#### **DOUBLE ROTARY**

In order to drill using casings, SOILMEC/PSM has developed a range of double rotaries that can be fitted to the lightest rig, the PSM 8GT and to the most specialised, the SM 30.

The possible diameters and depths depend on the nature of the soil and the type of rig to be used.

DR-816			
Upper retary	Torque	daNm	816
opper rotary	Speed	rpm	0-106
Lower rotary	Torque	daNm	1633
Lower rotary	Speed	rpm	0-53
DR-812			
Unnerretany	Torque	daNm	828
opper rotary	Speed	rpm	0-323
Lower rotary	Torque	daNm	1207
Lower rotary	Speed	rpm	0-221
DR-1018			
	Torque	daNm	1000
Upper rotary	Sneed	rnm	0-100
	Torque	daNm	1800
Lower rotary	Speed	rom	0-46
DD 4220			
DR-1220			
Upper rotary	Torque	daNm	1207
	Speed	rpm	0-221
Lower rotary	Torque	daNm	2025
· · · · · · · · · · · · · · · · · · ·	Speed	rpm	0-179
DR-1725			
linner rotary	Torque	daNm	1747
opperiotary	Speed	rpm	0-295
Lower rotary	Torque	daNm	2547
Lower rotary	Speed	rpm	0-52

	PSM-8GT	SM-14	PSM-20	SM-21	SM-30
DR-816					
DR-812					
DR-1018		•			
DR-1220					
DR-1725					

**N.B.** Other double rotary are in progress

#### **MECHANISED LOADING SYSTEMS**

Mechanised loading systems using either the carousel method or lateral positioning by means of the hydraulic piston, only depend on the auger used.

Compact design loaders with a variety of load capacities can be supplied with the whole range of the smaller rigs, from the PSM-8, that uses the elliptical three-auger loader for automatic manoeuvres up to 12 m in depth, to the SM-30 with the piston loader that can reach greater depths.

The Group has opted for cranes coupled with hydraulic clamps or special magnetic clamps for automatic loading of augers and casing tubes.

This choice makes it possible not to weight down the drill which would otherwise limit its flexibility and its operating sites, and above all, this means that there are no limitations on the drilling depth.

#### • Loader for elliptical three-auger rigs:

This has been designed specially for operation near supporting walls or escarpments in order to create "Berlin wall" supports. The bulk of the loader is contained within the geometry of the rotary.

- Diam. 76/90/114 mm L= 3000 (mounted on a PSM-8)
- Diam. 140 mm L= 3000 (mounted on a PSM-20)

#### • Piston loader:

housing two augers

- 2 x 6000 x 140 mm (mounted on a PSM-20)
- 2 x 7500 x 127 mm (mounted on a PSM-20)
- Carousel loader
- 10 x 3000 x 114 mm (mounted on SM-14)
- 6 x 4500 x 140 mm (mounted on PSM-20 and SM-21)
- 6 x 3000 x 140 mm (mounted on SM-21)
- 8 x 4500 x 114 mm (mounted on PSM-20)
- 10 x 4500 x 140 mm (mounted on SM-21)
- 10 x 3000 x 140 mm (mounted on SM-21 and PSM-20)



# **Drilling Foundation Tools**

#### RODS

Hydraulic drilling rigs for use in the microdrilling sector have been designed to allow for the use of different drilling technologies.

Different parameters must be considered in choosing the most suitable hydraulic rig for the technology involved.

The technical limit for hydraulic drilling rigs depends on:

- the rig's hydraulic and geometric potential
- the type of technology used and the soil to be drilled/consolidated

The flexibility and multi-use features of each drilling rig allows, depending on the machine, for operation outside these limits; operators and drillers should use common sense and experience to monitor such operations in terms of safety and machine life.

The attached tables aim to help the operator or driller correctly dimension the equipment as recommended by the manufacturer.



Diam. (mm)	Length (mm)	Thickness	ess Weight Thread			М	easur	es	
Α	В	В	kg.		С	D	E	F	G
76	1000	4	13	2.3/8 API	30	65	40	25	65
76	1500	4	17	2.3/8 API	30	65	40	25	65
76	2000	4	20	2.3/8 API	30	65	40	25	65
76	3000	4	24	2.3/8 API	30	65	40	25	65
76	1000	6,3	17	2.3/8 API	30	65	40	25	65
76	1500	6,3	23	2.3/8 API	30	65	40	25	65
76	2000	6,3	28	2.3/8 API	30	65	40	25	65
76	3000	6,3	39	2.3/8 API	30	65	40	25	65
89	1000	6,3	17	2.3/8 API	43	65	40	25	77
89	1500	6,3	24	2.3/8 API	43	65	40	25	77
89	2000	6,3	30	2.3/8 API	43	65	40	25	77
89	3000	6,3	43	2.3/8 API	43	65	40	25	77
89	1500	8,8	28	2.3/8 API	43	65	40	25	77
89	2000	8,8	35	2.3/8 API	43	65	40	25	77
89	3000	8,8	51	2.3/8 API	43	65	40	25	77
114	1000	6,3	26	3.1/2 API	43	95	50	30	75
114	1500	6,3	35	3.1/2 API	43	95	50	30	75
114	2000	6,3	43	3.1/2 API	43	95	50	30	75
114	3000	6,3	60	3.1/2 API	43	95	50	30	75
114	6000	6,3	110	3.1/2 API	43	95	50	30	75
114	1000	8,8	31	3.1/2 API	43	95	50	30	75
114	1500	8,8	42	3.1/2 API	43	95	50	30	75
114	2000	8,8	54	3.1/2 API	43	95	50	30	75
114	3000	8,8	77	3.1/2 API	43	95	50	30	75
114	6000	8,8	136	3.1/2 API	43	95	50	30	/5
114	7620	8,8	1/3	3.1/2 API	43	95	50	30	/5
127	1000	8,8	38	3.1/2 API	43	95	50	30	80
127	1500	8,8	51	3.1/2 API	43	95	50	30	80
127	2000	8,8	63	3.1/2 API	43	95	50	30	80
127	3000	8,8	90	3.1/2 API	43	95	50	30	80
127	6000	8,8	167	3.1/2 API	43	95	50	30	80
140	1000	8,8	45	4.1/2 API	58	120	50	30	100
140	1500	8,8	59	4.1/2 API	58	120	50	30	100
140	2000	8,8	73	4.1/2 API	58	120	50	30	100
140	3000	8,8	102	4.1/2 API	58	120	50	30	100
140	6000	8,8	187	4.1/2 API	58	120	50	30	100
140	7500	8,8	229	4.1/2 API	58	120	50	30	100
168	1500	8,8 (10)	92	4.1/2 API					
168	3000	8,8 (10)	140	4.1/2 API		0	n reque	st	
168	4500	8,8 (10)	190	4.1/2 API					

Different type of thread are available

### AUGERS

#### Auger with thread connection



Diam. (mm)	Pitch p	I-Thick. I	Tube dim. F	Attachment	L=1000 Weight (kg)	L=1500 Weight (kg)	L=3000 Weight (kg)
150	150	8	60	2-3/8A.R.	20	29	58
180	180	8	60	2-3/8A.R.	23	34	68
200	200	10	76	2-3/8A.R2-7/8A.R.	30	43	86
220	220	10	76	2-3/8A.R2-7/8A.R.	31	46	92
250	250	10	76	2-3/8A.R2-7/8A.R.	34	49	98
280	250	10	76	2-3/8A.R2-7/8A.R.	36	53	106
300	250	10	76	2-3/8A.R2-7/8A.R.	38	55	110
350	300	10-12	89	3-1/2A.R.	45	68	136
400	350	10-12	89	3-1/2A.R.	55	75	150

#### Auger exagonal pin connection



Diam. (mm)	Pitch p	l-Thick I	Tube dim. F	Attachment	L=1000 Weight (kg)	L=1500 Weight (kg)	L=3000 Weight (kg)
150	150	8	60	41	20	29	58
180	180	8	60	41	23	34	68
200	200	10	76	55	30	43	86
220	220	10	76	55	31	46	92
250	250	10	76	55	34	49	98
280	250	10	76	55	36	53	106
300	250	10	76	55	38	55	110
350	300	10-12	89	55	45	68	136
400	350	10-12	89	55	55	75	150

#### **BITS AND TRI-CONES**

Drilling tools such as blade bits or tri-cones are used for single rotary drilling with drilling polymers or muds or compressedair drainage; instrument design and material depend on the materials to be drilled.

#### **Blade bits**

Blade bits perform best in unconsolidated formations e.g. clay, sand and marl. Usually manufactured from high quality alloy steel, the blades are reinforced with tungsten carbide inserts.

#### **Tooth tri-cones**

Tooth tri-cones are used for soft, medium-soft and medium-hard formations. The tool's shoulders are usually reinforced. Teeth vary in form and layout to optimise feed in different soil types.

#### Tri-cones with tungsten carbide inserts

These are used for hard and abrasive soil and can perform for longer periods and at different penetration speeds than tooth models, as they can bear higher weights.

Bit type	Applicable formations	Weight per inch	Reccomended rotary speed	
Blade	Clay, sand, marl	-	min 60 - max 150	
	Soft and medium-soft	Min 450 kg - Max 1300 kg	min 60 - max 110	
Tooth tri-cone	Medium-hard	Min 450 kg - Max 1800 kg	min 50 - max 100	
	Hard	Min 900 kg - Max 2200 kg	min 40 - max 80	
	Medium soft	Min 450 kg - Max 1800 kg	min 45 - max 80	
Tri-cone with tungsten	Medium-hard	Min 1200 kg - Max 2800 kg	min 40 - max 80	
	Abrasive hard	Min 1800 kg - Max 3100 kg	min 30 - max 60	

### DTH DRILLING - APPLICABLE DIAMETERS AND COMPRESSED AIR CONSUMPTION

DTH (Down-the-hole) technology using a DTH hammer performs best for drilling rocky, medium rocky or alluvial material. Drilling is achieved using the hammer and an energy source (compressed air). Performance depends on the hammer and compressed air and the hydraulic rig is only used to transmit motion and execute drilling manoeuvres.

However, it is important to take into account the stresses on the drilling rigs and the correct DRILLING RIG - COMPRESSED AIR - DTH HAMMER relationship.

<b>DTH</b> Hammer type	Attachment	Reccomended rods (diam.) mm	Diameter range	Air consumption 7 bar l/min	Air consumption 10.5 bar l/min	Air consumption 14 bar l/min	Air consumption 17.6 bar I/min	Air consumption 21 bar I/min	Air consumption 24 bar I/min	SM/PSM drill range reccomended
3″	2-3/8	76	90-102	1	3500	5200	7200	9200	11800	PSM-8 / PSM-8B
4″	2-3/8	(76)-90	105-127	/	4700	6700	8500	10900	13500	PSM-8G / SM-30
5″	3-1/2		130-165	/	6800	9200	12000	15300	18700	SM-14 / PSM-20 SM-21 / PSM-8GT
6″	3-1/2	(90)-114-(140)	152-203	/	8800	12200	15600	19800	24600	PSM-16GT
6" HD	3-1/2	114-140 (168)	152-216 (229-305) (without bit guarantee)	1	10000	14000	17000	20500	26000	SM-14 SM-21
8″	4-1/2	140-168	204-270 (302-305) (without bit guarantee)	1	16000	20400 (23400)	26000 (31000)	31500 (38000)	36000 (45300)	PSM-20 PSM-16GT
10″	6-5/8	1	251-312	1	24100	34300	45600	1	1	PSM-20 / PSM-16GT SM-21 / SM-30 (shock absorber reccomended)
12″	6-5/8	1	312-445 (508-556) (without bit guarantee)	22100	30200	42500	53800	1	/	SM-30
12" HD	6-5/8 (N-25)	1	/	24000	36800	5100	65000	1	1	(shock absorber reccomended)
18″	8-5/8 (C-180)	C-180	1	38300	58700	77900	1	1	1	

The tables below are intended as user guides.

#### **DTH CASING DRILLING**

Hole instability requires drilling with casings. The most common systems are:

**DUPLEX:** The casing is rotated by the rotary head using a special twisting system.

A shoe is welded to the end of the tube at the bottom of the hole to facilitate feed. A drill string rotates (powered by the same upper rotary head) inside the casings, consisting of the drilling rods with a DTH hammer extending a few centimetres beyond the drill shoe.

This type of drilling is always performed using single rotary hydraulic drilling rigs and may also be used for rotary drilling with drilling fluids.

**TUBEX; ODEX; SIMMETRIX; SUPERJAWS:** These drilling systems have different characteristics depending on the manufacturer and use an eccentric bit with casing drawn by devices placed in the hole floor. The upper rotary head of the hydraulic drilling rig is used only to rotate the drill string, which operates wholly within the casings.

The double rotary drilling system allows for rotary-only operation with mud circulation as well as DTH hammer drilling. In both technologies, drilling is performed by the upper rotary head, which turns the rod/tri-cone or rod/DTH hammer drill string in a clockwise direction.

The bottom rotary turns the casing in an anti-clockwise direction.

Torque values are higher for the bottom rotary (which is subject to greater stresses) than for the upper rotary (which operates within the casing and is exposed to less friction and stress).

The fact that the two rotary heads turn in opposite directions has two benefits:

a) It avoids unscrewing the casing;

b) Inverse rotation provides the sum of two relative speeds. This results in increased hole-clearing as the spiral effect facilitates the drainage of drilling detritus.

		_	-		
	11 10				
	(ITT)				
	Fil		1	2	
		-			
4					
0	2			9	



Casing twisters								
Diameters	<b>Weight</b> kg	<b>Inner passage</b> mm	<b>Weight</b> kg					
D.114,3	8	76 2"3/8 API REG.	10					
D.127	9	76 2"3/8 API REG.	10					
D.139,7	11	76 2"3/8 API REG.	10					
		90 2 " 3/8 API REG.	14					
D.152,4	12	76 2"3/8 API REG.	10					
		90 2 "3/8 API REG.	14					
D.168,3	16	90 2 "3/8 API REG.	14					
		114 3 "1/2 API REG.	22					
D.177,8	17	90 2 "3/8 API REG.	14					
		114 3 "1/2 API REG.	22					
D.193,7	18	90 2 "3/8 API REG.	14					
		114 3 "1/2 API REG.	22					
D.203	19	90 2 " 3/8 API REG.	14					
		114 3 "1/2 API REG.	22					
D.219,1	21	114 3 "1/2 API REG.	22					
		127 3 "1/2 API REG.	24					
		140 4 "1/2 API REG.	27					
D.244,5	24	140 4 "1/2 API REG.	27					
D.273	27	140 4 "1/2 API REG.	27					
D.300	30	140 4 " 1/2 API REG.	27					

### **DTH CASING DRILLING**



**N.B.:** When assembling drill string, check thread and rotation direction of the casings and drilling rods.

Casings									
Diameters	Wall thickness mm	<b>Inner passage</b> mm	<b>Weight</b> kg						
D.114,3 L=1000	8,8	94	24						
D.114,3 L=1500	8,8	94	35						
D.114,3 L=3000	8,8	94	69						
D.127 L=1000	8,8	107	26						
D.127 L=1500	8,8	107	39						
D.127 L=3000	8,8	107	77						
D.139,7 L=1000	8,8	120	30						
D.139,7 L=1500	8,8	120	44						
D.139,7 L=3000	8,8	120	86						
D.152,4 L=1000	8,8	133	31,5						
D.152,4 L=1500	8,8	133	47						
D.152,4 L=3000	8,8	133	94						
D.168,3 L=1000	8,8	147	36						
D.168,3 L=1500	8,8	147	53						
D.168,3 L=3000	8,8	147	105						
D.177,8 L=1000	8,8	158	38						
D.177,8 L=1500	8,8	158	56						
D.177,8 L=3000	8,8	158	110						
D.193,7 L=1000	8,8	172	41						
D.193,7 L=1500	8,8	172	61						
D.193,7 L=3000	8,8	172	121						
D.203 L=1000	8,8	178	44						
D.203 L=1500	8,8	178	65						
D.203 L=3000	8,8	178	128						
D.219,1 L=1000	8,8	197	47						
D.219,1 L=1500	8,8	197	70						
D.219,1 L=3000	8,8	197	138						
D.244 L=1000	10	222	58						
D.244 L=1500	10	222	87						
D.244 L=3000	10	222	174						
D.273 L=1000	10	248	65						
D.273 L=1500	10	248	97						
D.273 L=3000	10	248	195						
D.300 L=1000	10	275	73						
D.300 L=1500	10	275	109						
D.300 L=3000	10	275	216						



Shoes									
Diameters		<b>Length</b> mm		<b>Inserts</b> n°	<b>Inner passage</b> mm	<b>Weight</b> kg	Туре		
114,3	117	93	160	12	10	3	KAL G.2		
127	130	105	160	12	10	3,5	KAL G.2		
139,7	143	119	160	14	10	4	KAL G.2		
152,4	155	131	160	14	10	4,5	KAL G.2		
168,3	170	146	160	16	10	4,7	KAL G.2		
177,8	180	157	160	16	10	4,9	KAL G.2		
193,7	195	172	160	18	10	5,5	KAL G.2		
203	204	177	160	18	10	6	KAL G.2		
219,1	222	196	160	20	10	7	KAL G.2		
244	245	222	160	24	10	8	KAL G.2		
273	274	248	160	26	10	9	KAL G.2		
300	300	274	160	28	10	9,5	KAL G.2		

### REMEMBER

Drilling with duplex down-the-hole system: rod thread right / casings right

Drilling with duplex muds system: rod thread right / casings right

Drilling with odex/ tubex system: rod thread right / driven tubes welded

Drilling with double rotary system: rod thread right / casings left
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## **CERTIFIED QUALITY SYSTEM**

In 1990 Soilmec was awarded with the certification of its Quality System complying with ISO 9001:2000 and ISO 14001:2004 standards.



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